

LOCATION	OBJECT CODE	LINE	SOURCE LINE
		59	PORT2 EQU 003H
	<0003>	60	DDR3 EQU 004H
	<0004>	61	DDR4 EQU 005H
	<0005>	62	PORT3 EQU 006H
	<0006>	63	PJRT4 EQU 007H
	<0007>	64	TCSR EQU 008H
	<0008>	65	TCSR_ICF EQU 10000000B
	<0009>	66	TCSR_OCF EQU 01000000B
	<0010>	67	TCSR_TUF EQU 00100000B
	<0011>	68	TCSR_EIC1 EQU 00010000B
	<0012>	69	TCSR_EIC2 EQU 00001000B
	<0013>	70	TCSR_ET01 EQU 00000100B
	<0014>	71	TCSR_IEDG EQU 00000010B
	<0015>	72	TCSR_OLVL EQU 00000001B
	<0016>	73	TIMER EQU 009H
	<0017>	74	OCR EQU 00BH
	<0018>	75	ICR EQU 00DH
	<0019>	76	P3CSR EQU 00FH
	<0020>	77	RMCR EQU 010H
	<0021>	78	RMCR_CC1 EQU 00001000B
	<0022>	79	RMCR_CC0 EQU 00000100B
	<0023>	80	RMCR_SS1 EQU 00000010B
	<0024>	81	RMCR_SS0 EQU 00000001B
	<0025>	82	TRCSR EQU 011H
	<0026>	83	TRCSR_RDRF EQU 10000000B
	<0027>	84	TRCSR_ORFE EQU 01000000B
	<0028>	85	TRCSR_TDRE EQU 00100000B
	<0029>	86	TRCSR_RIE EQU 00010000B
	<0030>	87	TRCSR_RE EQU 00001000B
	<0031>	88	TRCSR_TIE EQU 00000100B
	<0032>	89	TRCSR_TE EQU 00000010B
	<0033>	90	TRCSR_WU EQU 00000001B
	<0034>	91	RDATA EQU 012H
	<0035>	92	TDATA EQU 013H
	<0036>	93	RAMCR EQU 014H
	<0037>	94	MOTORS EQU PORT1
	<0038>	96	FUDGE EQU PORT3
	<0039>	98	BITS EQU PORT4
	<0040>	100	BITS_TEST EQU 10000000B
	<0041>	101	BITS_SPOKES EQU 01000000B
	<0042>	102	BITS_DETENT EQU 00100000B
	<0043>	103	BITS_LEFT EQU 00010000B
	<0044>	104	BITS_BRAKE EQU 11110111B
	<0045>	105	BITS_LF EQU 11111011B
	<0046>	106	BITS_RIBBON EQU 11111101B
	<0047>	107	BITS_HAMMER EQU 111111110B
	<0048>	108	DATA
	<0049>	109	
	<0050>	110	
	<0051>	111	STACKSPACE RMB 59
	<0052>	112	STACK EQU \$-1
	<0053>	113	BUFFER_POINTER RMB 2
	<0054>	114	IF SHANNON
	<0055>	115	BUFFER_COUNT RMB 2

TIMER CONTROL AND STATUS REGISTER

TIMER REGISTER (16 BITS)
 OUTPUT COMPARE REGISTER (16 BITS)
 INPUT CAPTURE REGISTER (16 BITS)
 PORT 3 CONTROL AND STATUS REGISTER
 RATE AND MODE CONTROL REGISTER FOR SCI

TRANSMIT/RECEIVE CONTROL AND STATUS REGISTER

RECEIVE DATA REGISTER
 TRANSMIT DATA REGISTER
 RAM CONTROL REGISTER

PORT 1 IS USED FOR STEPPING MOTORS

PORT USED TO FUDGE DESIGN SPEEDS

PORT 4 IS USED FOR VARIOUS THINGS
 SELF-TEST INPUT BIT (0 = SELF-TEST)
 WHEEL HOME INPUT BIT (1 = HOME)
 PLATEN DETENT INPUT BIT
 LEFT MARGIN INPUT BIT (1 = LEFT MARGIN)
 PLATEN MOTOR BRAKE OUTPUT (0 = BRAKE ON)
 PLATEN MOTOR ADVANCE OUTPUT (0 = MOTOR ON)
 RIBBON ADVANCE SOLENOID (0 = SOLENOID ON)
 PRINT HAMMER (0 = SOLENOID ON)

ROOM FOR STACK
 INITIAL VALUE FOR STACK POINTER
 POINTER TO NEXT CHAK OUT OF BUFFER
 NUMBER OF CHAKS IN BUFFER

59
 \$-1
 2
 SHANNON
 2

RMB
 EQU
 RMB
 IF
 RMB

0000
 003B

LOCATION OBJECT CODE LINE SOURCE LINE

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116 ELSE
003D 117 BUFFER_COUNT RMB 1
118 ENDDIF
119 RMB 16
003E 120 BUFFER RMB 1
004E 121 PLATEN RMB 1
004F 122 PLATSTAT EQU 10000000B
<0080> 123 PLATSTAT_RUN1 EQU 01000000B
<0040> 124 PLATSTAT_RUN2 EQU 01000000B
<0020> 125 PLATSTAT_STOP EQU 00100000B
<0010> 126 PLATSTAT_SETTLE EQU 00010000B
0050 127 PLATSTAT_SETTLE EQU 00010000B
0051 128 PLATSTAT_SETTLE EQU 00010000B
0053 129 WHSTAT RMB 1
0054 130 WHSTAT_BUSY EQU 10000000B
<0080> 131 WHSTAT_CW EQU 01000000B
<0040> 132 WHSTAT_CCW EQU 01000000B
<0020> 133 WHEELTICKS RMB 1
0055 134 WHEELTICKS RMB 1
0056 135 WHEELTICKS RMB 1
0057 <0057> 136 WHEELTOGO EQU WHEELTOGO
0058 137 HAMMER RMB 1
0059 138 HAMSTAT RMB 1
<0080> 139 HAMSTAT_HFIRE EQU 10000000B
<0040> 140 HAMSTAT_HREL EQU 01000000B
<0020> 141 HAMSTAT_RFIRE EQU 00100000B
<0010> 142 HAMSTAT_RREL EQU 00010000B
<0001> 143 HAMSTAT_ODD EQU 00000001B
005A 144 HAMTICKS RMB 1
005B 145 CARRIAGE RMB 1
005C 146 CARSTAT RMB 1
<0080> 147 CARSTAT_BUSY EQU 10000000B
<0040> 148 CARSTAT_LEFT EQU 01000000B
<0020> 149 CARSTAT_SETTLE EQU 00100000B
005D 150 CARTICKS RMB 1
005E 151 CARGONE RMB 1
005F 152 CARTOGO RMB 1
0060 <005F> 153 CARPOS EQU CARTOGO
154 MODE RMB 1
<0080> 155 MODE_TEST EQU 10000000B
<0040> 156 MODE_REVERSE EQU 01000000B
0061 157 IMAGE RMB 1
0062 158 HOME_IMAGE RMB 1
0063 159 PHANTOM RMB 1
0064 160 CLOCK RMB 2
<0064> 161 WANT_TIMER EQU CLOCK
162 IF SHANNON
163 M_SIG RMB 1
164 M_LEN RMB 1
165 NET_IN_BUFF RMB 16
166 ENDDIF
167
168 * MISC. CONSTANTS.
169
<0008> 170 BS EQU 008H
<000A> 171 LF EQU 00AH
<000B> 172 VT EQU 00BH

```

ASCII BACKSPACE
ASCII LINE FEED
ASCII VERTICAL TAB --- CHAR 10 DO 1/2 LINEFEED

NUMBER OF CHARS IN BUFFER
THE CHARACTER BUFFER
COMMAND/RESULT FOR PLATEN ROUTINE
STATUS OF PLATEN ROUTINE
TICK COUNTER FOR PLATEN ROUTINE
TIMEOUT COUNTER TO SHUT DOWN LF MOTOR
COMMAND/RESULT FOR WHEEL ROUTINE
STATUS OF WHEEL ROUTINE
TICK COUNTER FOR WHEEL ROUTINE
DISTANCE WHEEL HAS TRAVELLED
DISTANCE LEFT TO TRAVEL
WHEEL POSITION WHEN NOT MOVING
COMMAND/RESULT FOR HAMMER ROUTINE
STATUS OF HAMMER ROUTINE
TICK COUNTER FOR HAMMER ROUTINE
COMMAND/RESULT FOR CARRIAGE ROUTINE
STATUS OF CARRIAGE ROUTINE
TICK COUNTER FOR CARRIAGE ROUTINE
DISTANCE CARRIAGE HAS TRAVELLED
DISTANCE LEFT TO TRAVEL
CARRIAGE POSITION WHEN NOT MOVING
CURRENT PRINTER MODE
SELF-TEST MODE
PRINT REVERSE DIRECTION MODE
IMAGE OF MOTOR OUTPUT PORT
IMAGE OF MOTOR PORT AT HOME
PHANTOM POSITION OF CARRIAGE
TIMER TO TURN OFF MOTORS
USED BY CARDELAY & WHEELDELAY

LOCATION	OBJECT	CODE	LINE	SOURCE	LINE
			173	C3	EQU 00DH
	<000D>		174	CD	EQU 00EH
	<000E>		175	SI	EQU 00FH
	<000F>		176	ESC	EQU 01BH
	<001B>		177	SP	EQU 020H
	<0020>		178	DEL	EQU 07FH
	<007F>		179		
	<0050>		180	PLWIDTH	EQU 80
	<0005>		181	HOME_SPOKE	EQU 5
			182		
			183	* SOME CONSTANTS BASED ON THE FREQUENCY OF THE CRYSTAL. BECAUSE THE	
			184	* ASSEMBLER IS LIMITED TO 16-BIT ARITHMETIC, THESE CALCULATIONS	
			185	* HAVE TO BE DONE BY HAND (UGH!).	
			186		
			187	*XTAL	EQU 400000
			188	*E	EQU XTAL/4
			189	*TICK	EQU E/2400
	<01A1>		190	TICK	EQU 417
	<001B>		191	MSEC11	EQU 27
	<0024>		192	MSEC15	EQU 36
			193		
			194	* SPEED AND ENERGY CONSTANTS.	
			195		
	<0064>		196	CARSETL	EQU 100
	<0047>		197	CARSPD1	EQU 71
	<0032>		198	CARSPD2	EQU 50
	<0029>		199	CARSPD3	EQU 41
	<0023>		200	CARSPD4	EQU 35
	<0020>		201	CARSPD5	EQU 32
	<001D>		202	CARSPD6	EQU 29
	<001B>		203	CARSPD7	EQU 27
	<0019>		204	CARSPD8	EQU 25
			205		
	<00A5>		206	WHSETL	EQU 165
	<0015>		207	WHSPD1	EQU 21
	<0012>		208	WHSPD2	EQU 18
	<000F>		209	WHSPD3	EQU 15
	<000D>		210	WHSPD4	EQU 13
	<000B>		211	WHSPD5	EQU 11
	<0009>		212	WHSPD6	EQU 9
	<0008>		213	WHSPD7	EQU 8
	<0007>		214	WHSPD8	EQU 7
			215		
	<0008>		216	E4	EQU 8
	<0007>		217	E3	EQU 7
	<0006>		218	E2	EQU 6
	<0005>		219	E1	EQU 5
	<0005>		220	HAMMEL	EQU 5
			221		
	<001B>		222	RIBFINE	EQU MSEC11
	<000A>		223	RIBREL	EQU 10
			224		
	<0006>		225	PL_SPEED	EQU 6
	<007D>		226	PL_BRAKE_COUNT	EQU 125
	<0001>		227	PL_SETTLE_COUNT	EQU 1
	<12C0>		228	PL_TIMEOUT	EQU 4800
			229		

ASCII CARRIAGE RETURN
 ASCII SHIFT OUT --- CHAR TO START REVERSE PRINT
 ASCII SHIFT IN --- CHAR TO CANCEL REVERSE PRINT
 ASCII ESCAPE -- CHAR TO PRINT "SPACE" PETAL
 ASCII SPACE
 ASCII DELETE

NUMBER OF PRINT COLUMNS ON PLATEN
 SPOKE NUMBER WHEN IN HOME POSITION

CRYSTAL FREQUENCY IN HZ
 FREQUENCY OF E CLOCK IN HZ
 NUMBER OF E CYCLES IN 1/2400 SEC (1 TICK)

NUMBER OF TICKS IN 11 MSEC
 NUMBER OF TICKS IN 15 MSEC

TICK COUNT TO SETTLE CARRIAGE MOTOR
 CARRIAGE SPEEDS IN TICKS PER STEP

TICK COUNT TO SETTLE WHEEL MOTOR
 WHEEL SPEEDS IN TICKS PER STEP

TICK COUNTS FOR HAMMER ENERGIES

TICK COUNT TO DE-ENERGISE HAMMER SOLENOID
 TICK COUNT TO ENERGISE RIBBON SOLENOID
 TICK COUNT TO DE-ENERGISE RIBBON SOLENOID

PLATEN MOTOR SPEED 0.0
 TICK COUNT TO BRAKE PLATEN MOTOR
 TICK COUNT TO LET MOTOR COAST TO A STOP
 # OF TICKS IN 2 SECOND TIMEOUT


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LOCATION OBJECT CODE LINE SOURCE LINE
003C 8604 LDAA #RMRK_CCO CONFIGURE SCI -- INTERRUPTS ON
003E 9710 STAA RMLR SET BAUD RATE AND MODE
0040 861A LDAA #TRCSR_TE_OR_TRCSR_RE_OR_TRCSR_RIE
0042 9711 STAA TRCSR
0044 8600 LDAA #0
0046 9708 STAA TCSCR
0048 HOME_THINGS
0048 0E CLI ENABLE INTERRUPTS
0049 B00190 JSR HOME THE CARRIAGE
004C 8601 LDAA #1 INIT THE PHANTOM COLUMN TO MATCH
004E 9763 STAA PHANTOM,D
0050 B001E3 JSR WHEELHOME
0053 9661 LDAA IMAGE,D
0055 9762 STAA HOME_IMAGE,D
0057 7C004E INC PLATEN
005A DC09 LDD TIMER
005C C301A1 ADDD #TICK
005F DD0B STD OCR
0061 8608 LDAA #TCSR_EDCI
0063 9708 STAA TCSCR
0065 SHANNON
0065 7D003D IF BUFFER_COUNT,D ARE THERE CHARS TO BE PRINTED?
0068 263B ELSE
006A 7D0000 TST BUFFER_COUNT,D ARE THERE CHARS TO BE PRINTED?
006D 2615 ENDF
0075 CE04A1 IF PRINT_ONE BRANCH IF SO
0078 DF3D IF 1-SHANNON
007A 8666 TST M_SIG HAS THE MAC SIGNALLED US?
007C 973D BNE COPY_BUFFER BRANCH IF SO
007E 7E00A5 JMP
310 ***** THIS IS THE START OF THE MAIN LOOP. *****
311 * THIS IS THE START OF THE MAIN LOOP.
312
313 * THE FIRST THING WE CAN DO IS SEE IF THERE ARE ANY CHARACTERS FROM
314 * THE SERIAL LINK READY TO BE MOVED INTO THE RING BUFFER.
315
316 MAIN
317
318 LDD SHANNON
319 ELSE BUFFER_COUNT,D ARE THERE CHARS TO BE PRINTED?
320 TST BUFFER_COUNT,D ARE THERE CHARS TO BE PRINTED?
321 ENDF
322 BNE BRANCH IF SO
323 IF 1-SHANNON
324 TST M_SIG HAS THE MAC SIGNALLED US?
325 BNE COPY_BUFFER BRANCH IF SO
326
327 * This routine is used to point the buffer to the string if the
328 * unit is in self-test mode. If not, it does nothing.
329
330 MAKE_CHARS
331 LDAA MODE,D GET THE MODE BYTE
332 BITA #MODE_TEST SELF-TEST MODE?
333 BEQ JNO_CHAR BRANCH IF NOT
334 ENDF
335 LDX #STRING ELSE SET THE POINTER TO THE STRING
336 STX BUFFER_POINTER,D
337 IF SHANNON
338 LDD #STRING_END-STRING SET THE BYTE COUNT
339 STD BUFFER_COUNT,D
340 ELSE
341 LDAA #STRING_END-STRING SET THE BYTE COUNT
342 STAA BUFFER_COUNT,D
343 JMP PRINT_ONE AND 60 PRINT IT

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LOCATION OBJECT CODE LINE SOURCE LINE

00DE 8A40	401	URAA	#MODE_REVERSE	SET REVERSE MODE BIT
00E0 9760	402	STAA	MODE,D	
00E2 206F	403	BRA	INC	
00E4	404	SPACE		
00E4 9660	405	LDA	MODE,D	GET THE MODE BYTE
00E6 8540	406	RITA	#MODE_REVERSE	CHECK FOR REVERSE MODE
00E8 2611	407	BNE	GORIGHT	BRANCH IF REVERSE MODE IN EFFECT
00EA 9663	408	LDA	PHANTOM,D	GET THE PHANTOM COLUMN NUMBER
00EC 8150	409	CMPA	#PLWIDTH	IS THERE ROOM TO GO TO THE RIGHT?
00EE 2263	410	BHI	INC	BRANCH IF NOT
00F0 7C0063	411	INC	PHANTOM	ELSE INC. IT
00F3 205E	412	BRA	INC	
00F5	413	BACKSPACE		
00F5 9660	414	LDA	MODE,D	GET THE MODE BYTE
00F7 8540	415	RITA	#MODE_REVERSE	CHECK FOR REVERSE MODE
00F9 26EF	416	BNE	GORIGHT	BRANCH IF REVERSE MODE IN EFFECT
00FB 9663	417	LDA	PHANTOM,D	GET THE PHANTOM COLUMN NUMBER
00FD 8101	418	CMPA	#1	IS THERE ROOM TO GO TO THE LEFT
00FF 2352	419	BLS	INC	BRANCH IF NOT
0101 7A0063	420	DEC	PHANTOM	ELSE DEC. IT
0104 204D	421	BRA	INC	
0106	422	RETURN		
0106 9660	423	LDA	MODE,D	GET THE MODE BYTE
0108 84BF	424	ANDA	#OFFH-MODE_REVERSE	CHECK FOR REVERSE MODE
010A 9760	425	STAA	MODE,D	
010C 8601	426	LDA	#1	SET THE COLUMN NUMBER
010E 9763	427	STAA	PHANTOM,D	
0110 2041	428	BRA	INC	
0112	429	LINEFEED		
0112 964E	430	LDA	PLATEN,D	GET THE PLATEN COMMAND/RESULT BYTE
0114 81FF	431	CMPA	#OFFH	IS IT ALREADY FULL?
0116 27FA	432	BEQ	LINEFEED	WAIT FOR IT IF SO
0118 7C004E	433	INC	PLATEN	ELSE INC. IT TWICE
011B	434	HALF_LINEFEED		
011B 964E	435	LDA	PLATEN,D	GET THE PLATEN COMMAND/RESULT BYTE
011D 81FF	436	CMPA	#OFFH	IS IT ALREADY FULL
011F 27FA	437	BEQ	LINEFEED	WAIT FOR IT IF SO
0121 7C004E	438	INC	PLATEN	ELSE INC. IT
0124 202D	439	BRA	INC	
0126	440	ESCAPE		
0126 8620	441	LDA	#SP	GET A SPACE AS THOUGH IT WERE PRINTABLE
0128	442	PRINTABLE		
0128 D663	443	LDAB	PHANTOM,D	CHECK THE COLUMN NUMBER
012A C150	444	CMPB	#PLWIDTH	HAVE WE PAST THE LAST COLUMN?
012C 2225	445	BHI	INC	BRANCH IF SO -- CAN'T PRINT HERE
012E 9753	446	STAA	WHEEL,D	GIVE THE CHARACTER TO THE WHEEL ROUTINE
0130	447	PRINTABLE1		
0130 7D005B	448	TST	CARRIAGE	IS THE CARRIAGE MOVING


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LOCATION OBJECT CODE LINE SOURCE LINE
0133 26FB BNE PRINTABLE1 WAIT IF IT IS
0135 D663 LDAB PHANTOM,D THEN TELL IT WHERE TO GO
0137 D75B STAB CARRIAGE,D
0139 FIRE_WAIT1
0139 D653 LDAB WHEEL,D WAIT FOR ALL MOTION TO CEASE
013B D65B DRAB CARRIAGE,D
013D DA4E DRAB PLATEN,D
013F 26F8 DRAB HAMMER,D
0141 CE0577 BNE FIRE_WAIT1
0144 16 LDX #ENERGIES POINT TO THE HAMMER ENERGY TABLE
0145 C020 SUBB #SP REMOVE PRINTABLE OFFSET
0147 3A ABX ADD OFFSET TO THE TABLE ADDRESS
0148 A600 LDA 0,X GET THE ENERGY
014A 975B STAA HAMMER,D TELL THE HAMMER TO FIRE
014C FIRE_WAIT2
014C 7D0058 TST HAMMER IS THE HAMMER FINISHED
014F 26FB BNE FIRE_WAIT2 LOOP IF NOT
0151 2091 BRA SPACE THEN MOVE THE CARRIAGE
0153 INC
0153 DE3B LDX BUFFER_POINTER,D GET THE POINTER
0155 0B JNX INC. IT
0156 DF3B STX BUFFER_POINTER,D UPDATE MEMORY
IF SHANNON
0158 7A003D LDX BUFFER_COUNT,D DEC. THE CHAR COUNT
015B 7E0065 DEX BUFFER_COUNT,D
STX BUFFER_COUNT,D
DEC. THE CHAR COUNT
ENDIF
JMP MAIN AND LOOP FOR THE NEXT CHARACTER
IF 1-SHANNON
015E 7D005B NO_CHAR CARRIAGE IS THE CARRIAGE ALREADY IN MOTION
0161 26FB TST JMAIN BRANCH IF SO -- WE'LL LOOK AGAIN LATER
0163 9663 BNE PHANTOM,D ELSE GET ITS PROPER POSITION
0165 975B STAA CARRIAGE,D TELL CARRIAGE TO GO HERE
0167 C0FFF F LDD #OFFFHH SET THE TIMER
016A DD64 STD CLUCK,D
016C 7D0000 TIMEOUT
016F 26EA TST M_SIG HAS THE MAC ANYTHING FOR ME?
0171 DC64 BNE JMAIN BRANCH TO THE TOP IF SO
0173 26F7 LDD CLOCK,D HOW'S THE TIMER DOING
BNE TIMEOUT LOOP IF IT'S NOT ZERO YET

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LOCATION OBJECT CODE LINE SOURCE LINE
515 LDA #11111111B TURN OFF THE STEPPING MOTORS
516 STAA MOTORS
517 0177 9702
518
519 * NOW WE JUST SIT HERE WAITING FOR A CHARACTER TO ARRIVE.
520
521 Awaiting_CHAR M_SIG HAS THE BUFFER ANY NEWS?
522 TST Awaiting_CHAR . LOOP IF NOT
523 BEQ
524
525 * WHEN ONE DOES ARRIVE, WE RE-POWER THE MOTORS. BECAUSE THEY MIGHT
526 * HAVE SHIFTED POSITION WHILE THE POWER WAS OFF, WE HAVE TO HOME THE
527 * CARRIAGE AND THE DAISY WHEEL.
528
529 GOT_CHAR LDA #LAST_KNOWN_VALUE FOR THE MOTORS
530 IMAGE,D TURN THEM ON AGAIN
531 MOTORS HOME THE CARRIAGE
532 STAA JSR HOME THE WHEEL
533 CARHOME JSR
534 WHEELHOME
535 LDA HOME_IMAGE,D FORCE MOTORS TO SAME AS POWER-UP
536 STAA IMAGE,D
537 MOTORS
538 BRA JMAIN AND RETURN TO THE TOP OF THE LOOP
539 ENDF
540 *****
541 * CARHOME -- THIS ROUTINE MOVES THE CARRIAGE TO THE LEFT MARGIN.
542 * THE CARRIAGE IS MOVED AT A CONSTANT, SLOW SPEED WHILE WE WATCH FOR
543 * THE LEFT MARGIN SWITCH.
544
545 CARHOME
546
547 * FIRST WE MOVE THE CARRIAGE TO THE RIGHT, IN CASE IT IS LEFT OF THE
548 * LEFT MARGIN SWITCH.
549
550 BSR STEP_RIGHT MOVE ONE STEP RIGHT
551 BSR CAR_DELAY LET MOTOR SETTLE
552 LDA #BITS GET THE STATUS BYTE
553 BITA #BITS_LEFT LOOK AT THE LEFT MARGIN SWITCH
554 BNE CARHOME LOOP IF WE'RE STILL AT LEFT MARGIN
555
556 * AFTER WE'RE SURE WE'RE TO THE RIGHT OF THE DESIRED POSITION, WE
557 * CAN MOVE THE CARRIAGE LEFT UNTIL WE HIT THE LEFT MARGIN SWITCH.
558
559 CARHOME2
560 BSR STEP_LEFT MOVE ONE STEP LEFT
561 BSR CAR_DELAY LET MOTOR SETTLE
562 LDA #BITS GET THE STATUS BYTE
563 BITA #BITS_LEFT LOOK AT THE LEFT MARGIN SWITCH
564 BEQ CARHOME2 LOOP IF WE'RE NOT AT LEFT MARGIN
565
566 * THEN WE UPDATE THE POSITION BYTE TO REFLECT OUR NEW POSITION.
567
568 LDA #1 GET COLUMN NUMBER
569 STAA CARPOS,D AND SAVE IT
570
571 RTS

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LOCATION OBJECT CODE LINE SOURCE LINE

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572
573 *****
574 * STEP_LEFT -- THIS ROUTINE PERMUTES THE ORDER OF THE BITS IN THE
575 * MOTOR PORT FROM 76543210 TO 76540321, THUS MOVING THE CARRIAGE
576 * ONE STEP TO THE LEFT.
577
578 STEP_LEFT
579 LDA 9661 LDAA IMAGE,D
580 TAB TAB
581 LSRA LSLA
582 LSRL LSLB
583 LSLB LSLB
584 LSLB LSLB
585 ANDA ANDA
586 ANDB ANDB
587 ABA ABA
588 LDAB LDAB
589 ANDB ANDB
590 ABA ABA
591 STAA STAA
592 STAA STAA
593 RTS RTS
594
595 *****
596 * STEP_RIGHT -- THIS ROUTINE PERMUTES THE ORDER OF THE BITS IN THE
597 * MOTOR PORT FROM 76543210 TO 76542103, THUS MOVING THE CARRIAGE
598 * ONE STEP TO THE RIGHT.
599
600 STEP_RIGHT
601 LDA 9661 LDAA IMAGE,D
602 TAB TAB
603 LSRL LSLA
604 LSRB LSRB
605 LSRB LSRB
606 LSRB LSRB
607 ANDA ANDA
608 ANDB ANDB
609 ABA ABA
610 LDAB LDAB
611 ANDB ANDB
612 ABA ABA
613 STAA STAA
614 STAA STAA
615 RTS RTS
616
617 *****
618 * CAR_DELAY -- A ROUTINE TO DELAY FOR THE APPROPRIATE TIME SO AS TO
619 * PROVIDE A SLOW STEPPING RATE TO THE CARRIAGE MOTOR.
620
621 CAR_DELAY
622 LDD DC09 TIMER
623 ADDD C373A7 #CARSPD1*CLK
624 SLD WANT_TIMER,D
625 CAR_DELAY2
626 LDD DC09 TIMER
627 SUBD 9364 WANT_TIMER,D
628 BML BML

```

GET THE CURRENT PATTERN
 PUT INTO BOTH ACCUMULATORS
 MOVE SOME BITS ONE POSITION RIGHT
 MOVE OTHER BITS 3 PLACES LEFT

PICK OUT THE BITS WE WANT
 MIX THEM TOGETHER

PICK UP THE BITS THAT DON'T MOVE
 MIX THEM IN TOO
 UPDATE THE IMAGE
 UPDATE THE PORT

GET THE CURRENT PATTERN
 PUT INTO BOTH ACCUMULATORS
 MOVE SOME BITS ONE POSITION LEFT
 MOVE OTHER BITS 3 PLACES RIGHT

PICK OUT THE BITS WE WANT
 MIX THEM TOGETHER

PICK UP THE BITS THAT DON'T MOVE
 MIX THEM IN TOO
 UPDATE THE IMAGE
 UPDATE THE PORT

GET THE CURRENT TIMER VALUE
 CALCULATE DESIRED TIMER VALUE
 AND SAVE IT
 GET THE CURRENT TIMER VALUE
 COMPARE IT TO DESIRED VALUE
 LOOP IF NOT YET

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LOCATION OBJECT CODE LINE SOURCE LINE
01E2 39 629 RTS
630
631 * WHEELHOME -- THIS ROUTINE MOVES THE WHEEL TO ITS HOME POSITION.
632 * THE WHEEL IS MOVED AT A CONSTANT, SLOW SPEED WHILE WE WATCH FOR
633 * THE WHEEL HOME SENSOR.
634 *
635 WHEELHOME
636
637 * FIRST WE MOVE THE WHEEL TO MAKE SURE IT IS NOT AT THE HOME POSITION.
638
639 BSR ROT_CCW MOVE ONE STEP
640 BSR WHEEL_DELAY LET MOTOR SETTLE
641 LDAA #BITS GET THE STATUS BYTE
642 BITA #BITS_SPOKES LOOK AT THE WHEEL HOME SWITCH
643 BNE WHEELHOME LOOP IF WE'RE STILL AT HOME POSITION
644
645 * AFTER WE'RE SURE WE'RE NOT AT THE HOME POSITION, WE CAN ROTATE THE
646 * WHEEL INTO THE PROPER POSITION. THE REASON FOR THE DOUBLE CHECK IS
647 * SO THAT WE AVOID ANY ERRORS DUE TO THE WIDTH OF THE LITTLE FINGER
648 * WHICH TRIPS THE HOME SENSOR. BY DOING IT THIS WAY WE ARE ALWAYS
649 * LOOKING FOR THE SAME EDGE OF THE FINGER, AND ITS WIDTH HAS NO EFFECT.
650
651 WHEEL2
652 BSR ROT_CCW MOVE ONE STEP
653 BSR WHEEL_DELAY LET MOTOR SETTLE
654 LDAA #BITS GET THE STATUS BYTE
655 BITA #BITS_SPOKES LOOK AT THE WHEEL HOME SWITCH
656 BEQ WHEEL2 LOOP IF WE'RE NOT AT HOME POSITION
657
658 * THEN WE UPDATE THE POSITION BYTE TO REFLECT OUR NEW POSITION.
659
660 LDAA #HOME_SPOKE GET THE HOME SPOKE NUMBER
661 STAA WHEELPOS,D AND SAVE IT
662
663 RTS
664
665 *
666 *
667 * ROT_CCW -- THIS ROUTINE PERMUTES THE ORDER OF THE BITS IN THE
668 * MOTOR PORT FROM 76543210 TO 65473210, THUS MOVING THE WHEEL
669 * ONE STEP COUNTER-CLOCKWISE.
670
671 ROT_CCW
672 LDAA IMAGE,D GET THE CURRENT PATTERN
673 TAB PUT INTO BOTH ACCUMULATORS
674 LSLA MOVE SOME BITS ONE POSITION LEFT
675 LSRB MOVE OTHER BITS 3 PLACES RIGHT
676 LSRB
677 LSRB
678 ANDA #11100000B PICK OUT THE BITS WE WANT
679 ANDB #00010000B MIX THEM TOGETHER
680 ABA
681 LDAB IMAGE,D
682 ANDB #00001111B PICK UP THE BITS THAT DON'T MOVE
683 ABA MIX THEM IN TOO
684 STAA IMAGE,D UPDATE THE IMAGE
685 STAA MOTORS UPDATE THE PORT

```

LOCATION OBJECT CODE LINE SOURCE LINE

```

686 0211 39 RTS
687
688 *****
689 * ROT_CW -- THIS ROUTINE PERMUTES THE ORDER OF THE BITS IN THE
690 * MOTOR PORT FROM 76543210 TO 47653210, THUS MOVING THE WHEEL
691 * ONE STEP CLOCKWISE.
692
693 ROT_CW
694 LDAA IMAGE,D
695 TAB
696 LSRB
697 LSLB
698 LSLB
699 LSLB
700 ANDA #01110000B
701 ANDB #10000000B
702 ABA
703 LDAB IMAGE,D
704 ANDB #00001111B
705 ABA
706 STAA IMAGE,D
707 STAA MOTORS
708 RTS
709
710 *****
711 * WHEEL_DELAY -- A ROUTINE TO DELAY FOR THE APPROPRIATE TIME SO AS TO
712 * PROVIDE A SLOW STEPPING RATE TO THE WHEEL MOTOR.
713
714 WHEEL_DELAY
715 LDD TIMER
716 ADDD #HSEC15*TICK
717 STD WANT_TIMER,D
718 WHEEL_DELAY2
719 LDD TIMER
720 SUBD WANT_TIMER,D
721 BMI WHEEL_DELAY2
722 RTS
723
724 *****
725 * THIS IS THE START OF THE LOOP WHICH RUNS EACH TIME THERE IS A
726 * TIMER COMPARE INTERRUPT (ABOUT 2400 TIMES PER SECOND).
727
728 INT_LOOP
729 LDAA TCSR
730 LDD TIMER
731 ADDD #TICK
732 STD UCR
733 CLR TCSR
734 CLI
735
736 * UPDATE THE CLOCK USED TO TIME THE MOTOR TURN-OFF PERIOD. IF IT
737 * IS ALREADY ZERO, DON'T CHANGE IT.
738
739 DEC_CLOCK
740 LDD CLOCK,D
741 BEQ DEC_CLOCK_END
742 SUBD #1

```

GET THE CURRENT PATTERN
 PUT INTO BOTH ACCUMULATORS
 MOVE SOME BITS ONE POSITION RIGHT
 MOVE OTHER BITS 3 PLACES LEFT

PICK OUT THE BITS WE WANT
 MIX THEM TOGETHER

PICK UP THE BITS THAT DON'T MOVE
 MIX THEM IN TOO
 UPDATE THE IMAGE
 UPDATE THE PORT

GET THE CURRENT TIMER VALUE
 CALCULATE DESIRED TIMER VALUE (IN CYCLES)
 AND SAVE IT

GET THE CURRENT TIMER VALUE
 COMPARE IT TO DESIRED VALUE
 LOOP IF NOT YET

READ THIS TO CLEAR THE FLAG
 GET CURRENT TIMER CONTENTS
 CALCULATE WHEN WE WANT ANOTHER INTERRUPT
 UPDATE COMPARE REGISTER
 BUT TURN OFF TIMER INTERRUPTS
 ALLOW SERIAL INTERRUPTS

GET CURRENT CONTENTS
 EXIT IF ZERO
 ELSE DECREMENT I

```

LOCATION OBJECT CODE LINE SOURCE LINE
024A DD64 743 STD CLOCK,D AND UPDATE IT
024C 744 DEC_CLOCK_END
746 * SEE IF IT'S TIME TO STEP THE DAISY WHEEL MOTOR. THIS PIECE OF
747 * CODE MAINTAINS ITS OWN STATUS SO THAT IT KNOWS WHAT IT WAS DOING
748 * THE LAST TIME WE CAME BY THIS WAY.
749
750 POSWHEEL
024C 751 LDAA WHSTAT,D GET THE STATUS BYTE
024C 9654 752 BITA #WHSTAT_BUSY LOOK AT THE ACTIVITY BIT
024E 8580 753 BNE WHEEL3 BRANCH IF WE WERE ALREADY DOING SOMETHING
0250 263C 754 LDAB WHEEL,D ELSE SEE IF WE'VE GOTTEN A NEW COMMAND
0252 D653 755 BEQ JMW_END BRANCH IF NOT -- NOTHING TO DO
0254 2736 756
757 * IF WE HAVE A NEW COMMAND, CONVERT THE ASCII VALUE INTO A SPOKE NUMBER.
758
0256 CE04F7 759 LDX #SPOKES-SP POINT TO THE TABLE (MINUS ASCII OFFSET)
0259 3A 760 ABX ADD OFFSET TO TABLE ADDRESS
025A E600 761 LDAB 0,X GET THE SPOKE NUMBER
762
025C D057 763 SUBB WHEELPOS,D SEE HOW FAR WE HAVE TO MOVE THE WHEEL
025E 2603 764 BNE WHEELXX BRANCH IF WE HAVE TO MOVE IT
0260 7E02E4 765 JMP WH_DONE BRANCH IF IT'S ALREADY WHERE WE WANT IT
766
767 * WE NOW HAVE A NUMBER IN THE RANGE -95 TO 95 INCLUSIVE (EXCEPT ZERO).
768 * TO OPTIMIZE WHEEL MOTION WE WANT TO CONVERT IT TO THE RANGE
769 * -47 TO 48 INCLUSIVE. IF IT IS BETWEEN -95 AND -48 WE'LL ADD 96.
770 * IF IT IS BETWEEN 49 AND 95 WE'LL SUBTRACT 96.
771
0263 2808 772 WHEELXX NEG BRANCH IF IT'S A NEGATIVE NUMBER
0265 C131 773 CMPB #49
0267 2D0A 774 BLT DIR BRANCH IF 0 < A < 49
0269 C060 775 SUBB #96 FIX IT IF A >= 49
026B 2006 776 BRA DIR
777
026D 778 NEG
779 CMPB #-48
026F 2E02 780 BGT DIR BRANCH IF -48 < A < 0
0271 CB60 781 ADDB #96 FIX IT IF A <= -48
782
783 * NOW, BASED ON THE RESULT FROM ABOVE, WE CAN DECIDE WHICH DIRECTION TO
784 * SPIN THE WHEEL.
785
0273 5D 786 DIR
0273 5D 787 TSTB
0274 2808 788 BMI CW BRANCH IF WE'RE GOING CLOCKWISE
0276 BAB0 789 ORAA #WHSTAT_BUSY SET THE ACTIVITY BIT
0278 848F 790 ANDA #0FEH-WHSTAT_CW CLEAR THE CLOCKWISE BIT (WE'RE GOING CCW)
027A 9754 791 STAA WHSTAT,D
027C 2005 792 BRA WH_SETVARS
793 CW
027E 794 ORAA #WHSTAT_BUSY.OR.WHSTAT_CW SET THE BUSY & CW BITS
0280 9754 795 STAA WHSTAT,D
0282 5D 796 NEGB MAKE THE DISTANCE POSITIVE
797
798 * NOW WE CAN INIT SOME OF THE VARS WE'LL BE USING WHILE MOVING THE
799 * WHEEL.

```

LOCATION OBJECT CODE LINE SOURCE LINE

```

800 WH_SETVARS
801 WHEELTOGO,D
802 WHEELGONE,D
803 #1
804 WHEELTICKS,D
805 WH_END
806 JWH_END BRA
807
808 * IF WE WERE ALREADY BUSY DOING SOMETHING, WE COME HERE TO CARRY ON.
809
810 WHEEL3
811 DEC
812 WHEELTICKS
813 WH_END
814 #WHSTAT_SETTLE
815 WH_DONE
816 #WHSTAT_CW
817 GO_CW
818 ROT_CW
819 WHEEL4
820 JSR
821 GO_CW
822 WHEEL4
823 INC
824 WHEELGONE
825 WHEELTICKS
826 WHEELGONE
827 WHEELTICKS
828 WHEELGONE
829 WHEELTICKS
830 WHEELGONE
831 WHEELTICKS
832 WHEELGONE
833 WHEELTICKS
834 WHEELGONE
835 WHEELTICKS
836 WHEELGONE
837 WHEELTICKS
838 WHEELGONE
839 WHEELTICKS
840 WHEELGONE
841 WHEELTICKS
842 WHEELGONE
843 WHEELTICKS
844 WHEELGONE
845 WHEELTICKS
846 WHEELGONE
847 WHEELTICKS
848 WHEELGONE
849 WHEELTICKS
850 WHEELGONE
851 WHEELTICKS
852 WHEELGONE
853 WHEELTICKS
854 WHEELGONE
855 WHEELTICKS
856 WHEELGONE

```

SET HOW FAR WE HAVE TO GO
SET HOW FAR WE'VE ALREADY GONE
FAKE OUT THE COUNTER
THEN EXIT -- THINGS HAPPEN NEXT TIME

DEC. THE TICK COUNTER
BRANCH IF IT'S NOT TIME TO DO ANYTHING
IS THE WHEEL SETTILING?
BRANCH IF SO -- WE'RE ALL DONE
ELSE LOOK AT THE DIRECTION BIT
BRANCH IF IT IS CLOCKWISE
ELSE STEP THE WHEEL COUNTER--CLOCKWISE

STEP THE WHEEL CLOCKWISE
WE'VE TAKEN ANOTHER STEP
AND WE'VE GOT ONE LESS TO GO
BRANCH IF WE'VE GOT ZERO TO GO

* TO FIGURE HOW LONG TO WAIT BEFORE THE NEXT STEP, WE HAVE TO SEE
* WHERE WE ARE IN OUR TRAVEL. CALCULATE THE EXPRESSION:
* MIN(WHEELGONE, WHEELTICKS) AND USE THE RESULT AS AN OFFSET
* INTO THE SPEED TABLE. THE NUMBER FROM THE TABLE BECOMES OUR
* NEW TICK COUNT.

GET ONE OF THE TERMS
COMPARE IT TO ANOTHER
BRANCH IF THE ONE WE HAVE IS SMALLER
ELSE GET THE OTHER ONE

COMPARE IT TO THE LAST TERM
BRANCH IF THE ONE WE HAVE IS SMALLER
ELSE GET THE LAST ONE

POINT TO THE SPEED TABLE
ADD THE OFFSET
GET THE TICK COUNT
SAVE IT
READ THE FUDGE VALUE
COMPLEMENT IT
SHIFT THE NYBBLE DOWN

ADD TO THE CALCULATED VALUE
AND SAVE THE NEW VALUE
AND LEAVE

* IF WE HAVE JUST ARRIVED AT OUR DESTINATION, WE CAN SET UP THE
* TICK COUNTER FOR THE SETTLING TIME, AND RESET THE STATUS FLAGS.

LOCATION OBJECT CODE LINE SOURCE LINE

```

857 * THIS IS ALSO A HANDY TIME TO STORE THE CURRENT WHEEL POSITION.
858
859 WH_SETTLE
02DE 86A5 LDA #WHSETL SET THE TICK COUNTER
02DE 86A6 STAA WHEELTICKS,D
02D0 9755 LDAB WHEEL,D GET THE SPOKE NUMBER AGAIN
02D2 D653 LDX #SPOKES-SP
02D4 CE04F7 ABX
02D7 3A O,X
02D8 E600 LDAB WHEELPOS,D AND SAVE THAT AS OUR CURRENT POSITION
02DA D757 STAB WHSTAT,D UPDATE THE STATUS
02DC 9654 LDAA #WHSTAT_SETTLE
02DE 8A20 ORAA WHSTAT,D
02E0 9754 STAA WHSTAT,D
02E2 2006 BRA WH_END AND EXIT
871
872 * IF WE HAVE JUST FINISHED LETTING THE WHEEL SETTLE, OR IF IT HAD
873 * NOWHERE TO GO, WE CAN RESET EVERYTHING AND PREPARE FOR THE NEXT
874 * TIME AROUND.
875
876 WH_DONE CLR WHEEL CLEAR THE COMMAND/STATUS BYTE
877 CLR WHSTAT AND SHOW WE ARE DONE
878 WH_END
879 WH_END
880
881 * THEN WE ENTER THE CODE WHICH POSITIONS THE CARRIAGE. THIS CODE
882 * MAINTAINS ITS OWN STATUS SO IT CAN RECALL WHAT IT WAS DOING
883 * THE LAST TIME IT RAN.
884
885 POSCAR
02EA 965C LDA CARSTAT,D GET THE STATUS BYTE
02EA 8580 BITA #CARSTAT_BUSY LOOK AT THE ACTIVITY BIT
02EE 2623 BNE CARRIAGE3 BRANCH IF WE WERE ALREADY DOING SOMETHING
02F0 D658 LDAB CARRIAGE,D ELSE SEE IF WE HAVE GOTTEN A NEW COMMAND
02F2 271D BEQ JCAR_END BRANCH IF NOT -- NOTHING TO DO
891
892 * IF THIS IS A NEW COMMAND, WE CAN INIT VARIOUS THINGS. FIRST THING
893 * TO DO IS SEE HOW FAR THE CARRIAGE WILL HAVE TO TRAVEL. NOTE THAT
894 * THE COMMAND BYTE IS A COLUMN NUMBER, BUT ALL INTERNAL CALCULATIONS
895 * ARE DONE IN MOTOR STEPS. THERE ARE TWO STEPS PER PRINT COLUMN.
896
897 SUBB CARPOS,D SEE HOW FAR WE HAVE TO GO
898 BEQ CAR_DONE BRANCH IF CARRIAGE IS ALREADY THERE
899
900 * WE NOW HAVE THE DISTANCE IN COLUMNS, IN THE RANGE -79 TO 79.
901 * THE SIGN OF THE NUMBER TELLS US WHICH WAY WE'RE GOING TO GO.
902 * PRESERVE THAT INFORMATION IN THE STATUS BYTE.
903
904 BMI CAR_LEFT BRANCH IF GOING LEFT
905 OKAA #CARSTAT_BUSY SET THE ACTIVITY BIT
906 ANDA #OFFH-CARSTAT_LEFT SHOW WE'RE NOT GOING LEFT
907 STAA CARSTAT,D
908 BRA CAR_SETVAKS
909 CAR_LEFT
910 OKAA #CARSTAT_BUSY.OR.CARSTAT_LEFT SHOW WE'RE BUSY GOING LEFT
911 STAA CARSTAT,D
912 NEG8 MAKE THE DISTANCE POSITIVE
913
02F4 D05F SUBB CARPOS,D SEE HOW FAR WE HAVE TO GO
02F6 2769 BEQ CAR_DONE BRANCH IF CARRIAGE IS ALREADY THERE
899
900 * WE NOW HAVE THE DISTANCE IN COLUMNS, IN THE RANGE -79 TO 79.
901 * THE SIGN OF THE NUMBER TELLS US WHICH WAY WE'RE GOING TO GO.
902 * PRESERVE THAT INFORMATION IN THE STATUS BYTE.
903
904 BMI CAR_LEFT BRANCH IF GOING LEFT
905 OKAA #CARSTAT_BUSY SET THE ACTIVITY BIT
906 ANDA #OFFH-CARSTAT_LEFT SHOW WE'RE NOT GOING LEFT
907 STAA CARSTAT,D
908 BRA CAR_SETVAKS
909 CAR_LEFT
910 OKAA #CARSTAT_BUSY.OR.CARSTAT_LEFT SHOW WE'RE BUSY GOING LEFT
911 STAA CARSTAT,D
912 NEG8 MAKE THE DISTANCE POSITIVE
913
02F8 2B08 BMI CAR_LEFT BRANCH IF GOING LEFT
02FA 8AB0 OKAA #CARSTAT_BUSY SET THE ACTIVITY BIT
02FC 84BF ANDA #OFFH-CARSTAT_LEFT SHOW WE'RE NOT GOING LEFT
02FE 975C STAA CARSTAT,D
0300 2005 BRA CAR_SETVAKS
0302
0302 8AC0 OKAA #CARSTAT_BUSY.OR.CARSTAT_LEFT SHOW WE'RE BUSY GOING LEFT
0304 975C STAA CARSTAT,D
0306 50 NEG8 MAKE THE DISTANCE POSITIVE
913

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LOCATION OBJECT CODE LINE SOURCE LINE

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914 * NOW WE CAN CONVERT THE DISTANCE (NOW IN THE RANGE 1 TO 79) INTO
915 * STEPS BY MULTIPLYING BY 2. ALTHOUGH THE 6001 HAS A NIFTY
916 * MULTIPLY INSTRUCTION, THIS CASE IS EASIER TO DO WITH A SHIFT.
917
918 CAR_SETVARS
919 LSLB
920 STAB CARTOGO,D
921 CLR CARGONE
922 LDAA #1
923 STAA CARTICKS,D
924 JCAR_END BRA CAR_END
925
926 * IF WE WERE ALREADY BUSY DOING SOMETHING, WE COME HERE TO CARRY ON.
927
928 CARRIAGE3
929 DEC CARTICKS
930 BNE CAR_END
931 BITA #CARSTAT_SETTLE IS THE CARRIAGE SETTLE
932 BNE CAR_DONE BRANCH IF 90 -- WE'RE ALL DONE NOW
933 BITA #CARSTAT_LEFT LOOK AT THE DIRECTION BIT
934 BNE GO_LEFT BRANCH IF IT IS LEFT
935 JSR STEP_RIGHT ELSE STEP THE CARRIAGE TO THE RIGHT
936 BRA CARRIAGE4
937 GO_LEFT
938 JSR STEP_LEFT STEP THE CARRIAGE TO THE LEFT
939 CARRIAGE4
940 INC CARGONE WE'VE TAKEN ANOTHER STEP
941 DEC CARTOGO AND WE'VE GOT ONE LESS TO GO
942 BEQ CAR_SETTLE BRANCH IF WE'VE GOT ZERO TO GO
943
944 * TO FIGURE HOW LONG TO WAIT BEFORE THE NEXT STEP, WE HAVE TO SEE
945 * WHERE WE ARE IN OUR TRAVEL. CALCULATE THE EXPRESSION:
946 * MIN( CARGONE, CARTOGO, 8 ) AND USE THE RESULT AS AN OFFSET
947 * INTO THE SPEED TABLE. THE NUMBER FROM THE TABLE BECOMES OUR
948 * NEW TICK COUNT.
949
950 LDAB CARTOGO,D
951 CMPB CARGONE,D
952 BLS CARRIAGES
953 LDAB CARGONE,D
954 CARRIAGES
955 CMPB #8
956 BLS CARRIAGE6
957 LDAB #8
958 CARRIAGE6
959 LDX #CANSPEEDS-1
960 ABX
961 LDAB 0,X
962 STAB CARTICKS,D
963 LDAB FUDGE
964 CUMB
965 ANDB #0FH
966 ADDB CARTICKS,D
967 STAB CARTICKS,D
968 BRA CAR_END
969
970 * IF WE HAVE JUST ARRIVED AT OUR DESTINATION, WE CAN SET UP THE

```

CONVERT COLUMNS TO STEPS
 SET HOW FAR WE HAVE TO GO
 SET HOW FAR WE'VE ALREADY GONE
 FAKE OUT THE TIMER
 THEN EXIT -- THINGS WILL HAPPEN NEXT TIME

DEC. THE TICK COUNTER
 BRANCH IF IT'S NOT TIME TO DO ANYTHING
 IS THE CARRIAGE SETTLE
 BRANCH IF 90 -- WE'RE ALL DONE NOW
 LOOK AT THE DIRECTION BIT
 BRANCH IF IT IS LEFT
 ELSE STEP THE CARRIAGE TO THE RIGHT
 STEP THE CARRIAGE TO THE LEFT
 WE'VE TAKEN ANOTHER STEP
 AND WE'VE GOT ONE LESS TO GO
 BRANCH IF WE'VE GOT ZERO TO GO

GET ONE OF THE TERMS
 COMPARE IT TO ANOTHER
 BRANCH IF THE ONE WE HAVE IS SMALLER
 ELSE GET THE OTHER ONE
 COMPARE IT TO THE LAST TERM
 BRANCH IF THE ONE WE HAVE IS SMALLER
 ELSE GET THE LAST ONE
 POINT TO THE SPEED TABLE
 ADD THE OFFSET
 GET THE TICK COUNT
 SAVE IT
 READ THE FUDGE PORT
 COMPLEMENT IT
 ZERO THE HIGH (WHEEL'S) NYBBLE
 ADD TO THE CALCULATED VALUE
 AND SAVE THE NEW VALUE
 AND LEAVE

LOCATION	OBJECT CODE	LINE	SOURCE LINE
		971	* TICK COUNTER FOR THE SETTILING TIME, AND RESET THE STATUS FLAGS.
		972	* THIS IS ALSO A HANDY TIME TO STORE THE CURRENT CARRIAGE POSITION.
		973	
		974	CAR_SETTLE
0351	8664		SET THE TICK COUNTER
0351	8664		LDA #CARSETL
0353	975D		CARRIAGE,D
0355	D65B		GET THE COLUMN AGAIN
0357	D75F		CARPOS,D
0359	965C		AND SAVE THAT AS OUR CURRENT POSITION
035B	8A20		UPDATE THE STATUS
035D	975C		CARSTAT,D
035F	2006		CARSTAT,D
		981	AND EXIT
		982	BRA
		983	CAR_END
		984	* IF WE HAVE JUST FINISHED LETTING THE CARRIAGE SETTLE, OR IF IT HAD
		985	* NOWHERE TO GO, WE CAN RESET EVERYTHING AND PREPARE FOR THE NEXT
		986	* TIME AROUND.
		987	
		988	CAR_DONE
0361	7F005B		CLR CARRIAGE
0364	7F005C		CLR CARSTAT
0367			CLEAR THE COMMAND/STATUS BYTE
		991	CLEAR THE FLAGS
		992	CAR_END
		993	* THEN WE GET TO THE CODE WHICH FIRES THE HAMMER AND ADVANCES THE RIBBON.
		994	* THE COMMAND BYTE FROM THE MAINLINE IS USED AS THE INITIAL VALUE FOR
		995	* THE COUNTER WHEN THE HAMMER SOLENOID IS ENERGISED. THIS WAY, THE
		996	* MAINLINE CAN CONTROL THE HAMMER ENERGY. THE ONLY TRICKY THING WE DO
		997	* IS THIS -- AFTER FIRING AND RELEASING THE HAMMER WE AUTOMATICALLY
		998	* FIRE THE RIBBON ADVANCE SOLENOID. HOWEVER, WE RETURN THE ZERO STATUS
		999	* TO THE MAINLINE BEFORE ADVANCING THE RIBBON. THIS WAY, THE MAINLINE
		1000	* CAN START MOVING THE WHEEL AND CARRIAGE AND PLATEN EVEN WHILE THE
		1001	* RIBBON ADVANCE SOLENOID IS FIRED, WHICH IS PERFECTLY ALRIGHT.
		1002	
		1003	FIREHAMMER
0367	9659		HAMSTAT,D
0367	9659		GET OUR STATUS BYTE
0369	85F0		#HAMSTAT_HFIRE.OR.HAMSTAT_RREL.OR.HAMSTAT_RFIRE.OR.HAMSTAT_RREL
036B	2616		BRANCH IF WE'RE ALREADY DOING SOMETHING
036D	9650		CONTINUE
036F	276A		HAMMER,D
0371			ELSE LOOK AT THE COMMAND BYTE
0371	975A		BEQ
0373	9607		BRANCH IF NOTHING TO DO
0375	84FE		ELSE SET THE COUNTER FOR HAMMER FIRE TIME
0377	9707		GET THE CURRENT PORT VALUE
0379	9659		TURN ON THE HAMMER BIT (0 = ON)
037B	8AB0		SHOW THE HAMMER IS FIRING
037D	8801		HAMSTAT,D
037F	9759		HAMSTAT,HFIRE
0381	2058		#HAMSTAT_HFIRE
		1011	FLIP THE EVERY-OTHER BIT
		1012	UPDATE THE STATUS
		1013	HAMSTAT,D
		1014	AND EXIT
		1015	BRA
		1016	
		1017	
		1018	
		1019	
		1020	* ARRIVE HERE IF WE WERE ALREADY DOING SOMETHING. DECREMENT THE
		1021	* TICK COUNTER TO SEE IF ANYTHING HAS TO BE CHANGED.
		1022	
		1023	CONTINUE
0383	7A005A		DEC THE TICK COUNTER
0386	2653		BRANCH IF NOT TIME TO DO ANYTHING
		1025	
		1026	
		1027	* OK, SO WE'VE DECIDED SOME ACTION NEEDS TO BE TAKEN. CHECK THE

LOCATION OBJECT CODE LINE SOURCE LINE

```

1028 * BITS IN HAMSTAT (CURRENTLY IN A) TO SEE WHAT WE WERE DOING AND
1029 > DECIDE WHAT COMES NEXT.
1030
1031 BITA #HAMSTAT_HFIRE WERE WE FIRING THE HAMMER?
1032 BNE HREL GO TO RELEASE IT IF SO
1033 BITA #HAMSTAT_HREL WERE WE RELEASING THE HAMMER?
1034 BNE RFIRE GO TO ADVANCE THE RIBBON IF SO
1035 BITA #HAMSTAT_RFIRE WERE WE ADVANCING THE RIBBON?
1036 BNE RREL GO TO RELEASE IT IF SO
1037 BITA #HAMSTAT_RREL WERE WE RELEASING THE RIBBON?
1038 BNE DUNE GO TO FINISH UP IF SO
1039
1040 * HERE WE RELEASE THE HAMMER SOLENOID AND RESET THE TICK COUNTER.
1041
1042 HREL
1043 ORAA #HAMSTAT_HREL SHOW OUR NEW STATUS
1044 ANDA #OFFH-HAMSTAT_HFIRE
1045 STAA HAMSTAT,D
1046 LDAA BITS GET THE PORT IMAGE
1047 ORAA #OFFH-BITS_HAMMER TURN OFF THE HAMMER BIT
1048 STAA BITS
1049 LDAA #HAMREL SET THE NEW COUNTER
1050 STAA HMTICKS,D
1051 BRA END
1052
1053 * HERE WE CLEAR THE COMMAND/STATUS BYTE AND FIRE THE RIBBON
1054 * ADVANCE SOLENOID.
1055
1056 RFIRE
1057 CLR HAMMER
1058 BITA #HAMSTAT_ODD TELL THE MAINLINE TO CARRY ON
1059 BEQ DONE IS THIS THE TIME TO FIRE THE RIBBON?
1060 ORAA #HAMSTAT_RFIRE SHOW OUR NEW STATUS BRANCH IF NOT
1061 ANDA #OFFH-HAMSTAT_HREL
1062 STAA HAMSTAT,D
1063 LDAA #BITS_RIBBON GET THE PORT IMAGE
1064 ANDA #BITS_RIBBON TURN ON THE RIBBON ADVANCE BIT
1065 STAA BITS
1066 LDAA #RIBFIRE SET THE NEW COUNTER
1067 STAA HMTICKS,D
1068 BRA END
1069
1070 * IN THIS SECTION WE RELEASE THE RIBBON ADVANCE SOLENOID.
1071
1072 RREL
1073 ORAA #HAMSTAT_RREL SHOW OUR NEW STATUS
1074 ANDA #OFFH-HAMSTAT_RFIRE
1075 STAA HAMSTAT,D
1076 LDAA BITS GET THE PORT IMAGE
1077 ORAA #OFFH-BITS_RIBBON TURN OFF THE RIBBON ADVANCE BIT
1078 STAA BITS
1079 LDAA #RIBREL SET THE NEW COUNTER
1080
1081 STAA HMTICKS,D
1082 BRA END
1083
1084 * IF WE ARE DONE ALL PHASES OF THIS THING, WE COME HERE TO

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LOCATION OBJECT CODE LINE SOURCE LINE
1085 * CLEAR OUR STATUS BYTE.
1086
1087 DONE
1088 LDA HAMSTAT,D TURN OFF THE OLD STATUS BITS
1089 ANDA #HAMSTAT_ODD
1090 STAA HAMSTAT,D
1091 END
1092
1093 * Then we get to this code which controls the linefeed mechanism.
1094 * If the contents of PLATEN is non-zero, it means we have to do
1095 * some linefeeds. This routine uses PLATSTAT to remember its
1096 * internal states between execution times.
1097 * THIS VERSION RUNS THE MOTOR FORWARD UNTIL THE SENSE SWITCH CLOSES,
1098 * RUNS UNTIL THE SWITCH OPENS, BRAKES FOR 255 TICKS, THEN IDLES.
1099
1100 PLATPOS
1101 LDA PLATSTAT,D GET OUR STATUS BYTE
1102 BNE PL_CONTINUE BRANCH IF WE'RE ALREADY DOING SOMETHING
1103 LDA PLATEN,D ELSE LOOK AT THE COMMAND BYTE
1104 BEQ PL_END_ISLE BRANCH IF NOTHING TO DO
1105
1106 LDA #PLATSTAT_RUN1 SET THE STATUS BYTE TO RUN MODE
1107 STAA PLATSTAT,D
1108 LDD #PL_TIMEOUT INIT FOR 2 SEC. TIMEOUT
1109 STD FIRE_PROOF FOR MOTOR RUN
1110 BRA PL_END_ISLE AND LEAVE
1111
1112 PL_CONTINUE
1113 BITA #PLATSTAT_RUN1 IS THE MOTOR RUNNING UNTIL CLOSURE?
1114 BNE PL_RUN1 BRANCH IF SO
1115 BITA #PLATSTAT_RUN2 ARE WE LETTING THE SWITCH OPEN?
1116 BNE PL_RUN2 BRANCH IF SO
1117 BITA #PLATSTAT_STOP IS THE MOTOR STOPPING?
1118 BNE PL_STOP BRANCH IF SO
1119 BITA #PLATSTAT_SETTLE IS THE MOTOR SETTling?
1120 BNE PL_SETTLE BRANCH IF SO
1121 BRA PL_END_ISLE THIS SHOULD NEVER RUN
1122
1123 * THIS PART RUNS THE MOTOR UNTIL THE SENSE INPUT GOES LOW (SWITCH CLOSES).
1124 * WE USE THE 3 LOWEST BITS OF PLATSTAT AS A COUNTER TO
1125 * DETERMINE WHEN TO TURN ON AND OFF THE MOTOR AS WE RUN IT
1126 * IN PULSED MODE.
1127
1128 PL_RUN1
1129 LDD FIRE_PROOF HAVE WE DIED YET?
1130 SUBD #1
1131 STD FIRE_PROOF
1132 BEQ WE_DIED GO AWAY
1133 JSR PULSE_MOTOR RUN THE MOTOR IN PULSED MODE
1134 LDA #BITS LOOK AT THE SENSE BIT
1135 BITA #BITS_DETENT
1136 BNE PL_END BRANCH IF IT'S STILL OPEN
1137 LDA #PLATSTAT_RUN2 ELSE GO TO RUN2 MODE
1138 STAA PLATSTAT,D
1139 LDD #PL_TIMEOUT
1140 STD FIRE_PROOF
1141 PL_END_ISLE
1142
1143 FC0051
1144 B30001
1145 FD0051
1146 B2765
1147 B00486
1148 B607
1149 B520
1150 B2656
1151 B8640
1152 B974F
1153 CC12C0
1154 FD0051
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LOCATION OBJECT CODE LINE SOURCE LINE
041F 204A 1142 BRA PL_END AND LEAVE
1143
1144 * THIS PART CONTINUES TO RUN THE MOTOR UNTIL THE SWITCH CLOSES
1145 * AGAIN.
1146 PL_RUN2
0421 FC0051 LDD FIRE_PROOF HAVE WE DIED YET?
0424 830001 SUBD #1
0427 FD0051 STD FIRE_PROOF
042A 2745 BEQ WE_DIED GO AWAY
042C ED0486 JSR PULSE_MOTOR RUN THE MOTOR
042F 9607 LDAA #BITS_READ THE REGISTER
0431 8520 BITA #BITS_DETENT LOOK AT THE SWITCH
0433 2736 BEQ PL_END BRANCH IF SWITCH IS STILL CLOSED
0435 9607 LDAA #OFFH-BITS_LF ELSE BRAKE THE MOTOR
0437 8A04 ORAA #OFFH-BITS_LF
0439 9707 STAA #BITS
043B 01 NOP
043C 01 NOP
043D 84F7 ANDA #BITS_BRAKE
043F 9707 STAA #BITS
0441 867D LDAA #PL_BRAKE_COUNT SET THE TICK COUNT
0443 9750 STAA #PLATTICKS,D
0445 8620 LDAA #PLATTICKS_STOP GO TO STOP MODE
0447 974F STAA #PLATTICKS_STOP
0449 2020 BRA PL_END
044B
044B 7A0050 PL_STOP PLATTICKS COUNT DOWN THE REVERSE TIME
044E 2618 BNE PL_END LEAVE IF MORE TO DO
0450 9607 LDAA #BITS ELSE TURN OFF THE MOTOR
0452 8A0C ORAA #((OFFH-BITS_BRAKE).OR.(OFFH-BITS_LF))
0454 9707 STAA #BITS
0456 8601 LDAA #PL_SETTLE_COUNT SET THE TICK COUNT
0458 9750 STAA #PLATTICKS,D
045A 8610 LDAA #PLATTICKS_STOP GO TO SETTLE MODE
045C 974F STAA #PLATTICKS_STOP
045E 2008 BRA PL_END
0460
0460 7A0050 PL_SETTLE PLATTICKS COUNT DOWN THE REVERSE TIME
0463 2606 BNE PL_END LEAVE IF MORE TO DO
0465 7F004F CLR PLATTICKS ELSE SHOW WE'RE DONE
0468 7A004E DEC PLATTEN ONE LINEFEED FINISHED
046B
1186 PL_END
1187
1188 ***** THIS IS THE CLEANUP AT THE END OF THE INTERRUPT ROUTINE. *****
1189 * THIS IS THE CLEANUP AT THE END OF THE INTERRUPT ROUTINE.
1190
1191 SETI DISABLE INTERRUPTS HERE
1192 LDAA #TCUSR_EDCI RE-ENABLE TIMER INTERRUPTS
1193 STAA TCSR
1194 RTI
1195 *****
1196 ***** IF WE GOT HERE, THE LF MOTOR TIMEDOUT. KILL ALL INTERRUPTS, *****
1197 * IF WE GOT HERE, THE LF MOTOR TIMEDOUT. KILL ALL INTERRUPTS,
1198 * TURN OFF MOTORS, AND GO TO SLEEP

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LOCATION OBJECT CODE LINE SOURCE LINE

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1199
1200 WE_DIED
1201     SEI
1202     LDAA
1203     STAA
1204     LDAA
1205     STAA
1206     LDAA
1207     STAA
1208     LDAA
1209     ORAA
1210     STAA
1211 INF_LOOP
1212     BKA
1213 *
1214 *
1215
1216 *****
1217 * THIS ROUTINE RUNS THE PLATEN MOTOR IN PULSED DRIVE MODE.
1218 * IT INCREMENTS PLATTICKS AND USES THE BOTTOM THREE BITS
1219 * TO DETERMINE WHETHER THE MOTOR SHOULD BE ON OR OFF.
1220
1221 PULSE_MOTOR
1222     INC
1223     LDAA
1224     ANDA
1225     CMPA
1226     BLO
1227 PL_RUN_OFF
1228     LDAA
1229     ORAA
1230     STAA
1231     RTS
1232 PL_RUN_ON
1233     LDAA
1234     ORAA
1235     ANDA
1236     STAA
1237     RTS
1238
1239     IF
1240
1241 *****
1242 * THIS IS THE STRING TO BE PRINTED IN SELF-TEST MODE.
1243
1244 STRING
1245     FCC
1246     FCB
1247     FCC
1248     FCB
1249     FCC
1250     FCB
1251     FCC
1252     FCB
1253     FCC
1254     FCB
1255     FCC

#0
TCSR          DISABLE TIMER INTERRUPTS
#RMCR_CDO     CONFIGURE SCI -- NO INTERRUPTS
#MCR         SET BAUD RATE AND MODE
#TRCSR_TE_OR,TRCSR_RE
TRCSR         TURN OFF THE LINEFEED MOTOR
BITS         #(<OFFH-BITS_BRAKE>.OR.<OFFH-BITS_LF>)
BITS
INF_LOOP     EVEN THOUGH WE HAVE ALL INTERRUPTS
            DISABLED, MAKE SURE WE NEVER COME
            BACK
*****
THIS ROUTINE RUNS THE PLATEN MOTOR IN PULSED DRIVE MODE.
IT INCREMENTS PLATTICKS AND USES THE BOTTOM THREE BITS
TO DETERMINE WHETHER THE MOTOR SHOULD BE ON OR OFF.
PULSE_MOTOR
INC          INC THE PULSE COUNTER
PLATTICKS,D GET THE COUNT.
LOOK ONLY AT THE BOTTOM 3 BITS
COMPARE IT TO OUR SPEED THRESHOLD
BRANCH IF THE MOTOR SHOULD BE ON
PL_RUN_OFF  TURN OFF THE MOTOR
BITS
#(<OFFH-BITS_BRAKE>.OR.<OFFH-BITS_LF>)
RTS
PL_RUN_ON   TURN ON THE MOTOR
BITS
#(<OFFH-BITS_BRAKE (MAKE SURE BRAKE IS OFF)
#BITS_LF
RTS
IF          SHANNON
*****
THIS IS THE STRING TO BE PRINTED IN SELF-TEST MODE.
STRING
FCC        'The head and in frontal attack on english writer
FCB        LF,SO
FCC        'rehtona erofereht si tniop siht fo retcarahc eht taht'
FCB        CR,LF
FCC        'method for the letters that the time of whoever told
FCB        LF,SO
FCC        'latnorf ni dna daeh eht .detcepxenu na rof melborp eht'
FCB        CR,LF
FCC        'attack on english writer that the character of
FCB        LF,SO
FCC        'taht srettel eht rof dohten rehtona erofereht si tniop siht'

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LOCATION OBJECT CODE LINE SOURCE LINE

0509 29 FCB CARSPD3
 1295 FCB CARSPD4
 050A 23 FCB CARSPD5
 1296 FCB CARSPD6
 050B 20 FCB CARSPD7
 1297 FCB CARSPD8
 050C 1D FCB
 1298
 050D 1B FCB
 1299
 050E 19 FCB

1300
 1301
 1302 *****
 1303 * THIS TABLE IS USED TO CALCULATE WHEEL MOTOR STEPPING TIMES.
 1304 * THE FIRST ENTRIES ARE USED FOR SLOWER SPEED, AS THE WHEEL LEAVES
 1305 * ITS STARTING POINT AND NEARS ITS DESTINATION. THE LAST ENTRY IS
 1306 * TOP SPEED USED DURING MOST OF THE TRANSIT.
 1307

050F 15 WHSPD1
 1308 FCB WHSPD2
 0510 12 FCB WHSPD3
 1309 FCB WHSPD4
 0511 0F FCB WHSPD5
 1310 FCB WHSPD6
 0512 0D FCB WHSPD7
 1311 FCB WHSPD8
 0513 0B FCB
 1312 FCB
 0514 09 FCB
 1313 FCB
 0515 08 FCB
 1314 FCB
 0516 07 FCB
 1315 FCB
 1316 FCB
 1317

1318 *****
 1319 * THIS TABLE RELATES ASCII CHARACTERS TO THEIR POSITIONS ON THE PRINT
 1320 * WHEEL. THE DATA APPLIES TO 96-CHARACTER PLASTIC WHEELS. TO USE THE
 1321 * TABLE, CALCULATE AN OFFSET WHICH IS CHAR - 020, HAND THE BYTE THERE
 1322 * IS THE SPOKE NUMBER WHERE THAT CHAR CAN BE FOUND. ALTHOUGH THE SPOKE
 1323 * FOR ASCII SPACE IS NOT NORMALLY PRINTED, IT IS INCLUDED HERE BECAUSE A
 1324 * SPECIAL CODE CAN BE USED TO ACCESS IT. VALID CHARACTERS ARE IN THE
 1325 * RANGE 020HD 07F. H
 1326

0517 0244462E20 FCB 2,68,70,46,44,47,69,54 to /
 1327 SPOKES
 1328
 051C 2F4536 FCB 60,58,61,45,3,43,5,66 (to /
 051F 3C3A3D2D03 FCB 37,33,34,35,36,38,39,40 0 to 7
 0524 2B0542 FCB 41,42,12,31,57,48,50,65 8 to
 052C 26272B FCB 62,11,8,10,22,15,9,24 @ to G
 052F 292A0C1F39 FCB 17,20,29,28,21,6,19,18 H to 0
 0534 303241 FCB 26,27,13,14,16,23,30,4 P to W
 0537 3E0B080A16 FCB 32,25,7,53,63,51,64,55 X to -
 053C 0F0918 FCB 56,84,78,79,76,83,89,74 \ to g
 0544 061312 FCB 87,85,72,93,77,71,82,80 h to o
 0547 1A1B0D0E10 FCB 90,92,81,88,86,91,73,0 p to w
 054C 171E04 FCB 75,94,95,49,59,67,52,1 x to DEL
 054F 201907353F FCB
 0554 334037 FCB
 0557 38544E4F4C FCB
 055C 53594A FCB
 055F 5755485D4D FCB
 0567 5A5C515856 FCB
 056C 5B4900 FCB
 056F 4B5E5F313B FCB
 0574 433401 FCB

LOCATION OBJECT CODE LINE SOURCE LINE

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1340
1341 *****
1342 * THIS TABLE GIVES THE HAMMER ENERGY FOR EACH PRINTABLE CHARACTER.
1343 * TO USE IT, CALCULATE AN OFFSET WHICH IS CHAK) - 020,HAND
1344 * THE BYTE THERE IS THE HAMMER ENERGY FOR THAT CHARACTER. VALID
1345 * CHARACTERS ARE IN THE RANGE 020H0 07F.H
1346
1347 ENERGIES
1348 FCB E3,E2,E2,E3,E3,E3,E1 to /
1349 FCB E2,E2,E3,E2,E1,E1,E2 ( to /
1350 FCB E3,E2,E3,E2,E3,E3,E2 0 to 7
1351 FCB E3,E3,E1,E2,E2,E3,E2,E2 8 to
1352 FCB E4,E3,E4,E3,E4,E4,E4,E4 @ to G
1353 FCB E4,E2,E3,E4,E4,E4,E4,E3 H to 0
1354 FCB E4,E4,E4,E3,E3,E4,E4,E4 P to W
1355 FCB E4,E4,E3,E2,E2,E2,E1,E2 X to -
1356 FCB E1,E2,E4,E2,E3,E2,E3,E4 \ to g
1357 FCB E3,E2,E3,E3,E2,E4,E3,E3 h to o
1358 FCB E4,E4,E2,E3,E2,E3,E2,E3 p to w
1359 FCB E3,E4,E3,E2,E2,E2,E1,E1 x to DEL)
1360
1361
1362 *****
1363 * This is a null interrupt routine that we can aim the unused interrupt
1364 * vectors at. It should never be executed, but better to have it than
1365 * to have the machine hang...
1366
1367 NULL
1368 RTI
1369
1370 *****
1371 * THESE ARE THE VECTORS FOR THE 6801. MANY ARE UNUSED IN THIS SOFTWARE,
1372 * SO THEY JUST POINT TO A NULL INTERRUPT ROUTINE.
1373
1374 IF 1-SHANNON
1375 ORG OFFF0H SCI INTERRUPT
1376 FDB PR_MAC
1377 ENDIF
1378 ORG OFFF4H
1379 FDB INT_LOOP TIMER COMPARE
1380 ORG OFFFEH
1381 FDB RESET RESET
1382
1383
05D7
05D7 3B
FFF0 0000
FFF4 0236
FFFE 0000

```

LOCATION OBJECT CODE LINE SOURCE LINE

Errors= 0

LINE#	SYMBOL	TYPE	REFERENCES
521	AWAIT_CHAR	P	523
416	BACKSPACE	P	381
99	BITS	A	258,269,552,562,642,655,1011,1013,1046,1048,1063,1065,1076,1078,1134,1152,1155,1157,1161,1171,1173,1208,1210,1228,1230,1233,1236
104	BITS_BRAKE	A	1160,1172,1209,1229,1234
102	BITS_DETENT	A	1135,1153
107	BITS_HAMMER	A	1012,1047
103	BITS_LEFT	A	553,563
105	BITS_LF	A	1156,1172,1209,1229,1235
106	BITS_RIBBON	A	1064,1077
101	BITS_SPOKES	A	643,656
100	BITS_TEST	A	270
170	BS	A	380
119	BUFFER	D	
115	BUFFER_COUNT	D	318,339,488,490
113	BUFFER_POINTER	D	336,368,484,486
151	CARGONE	D	921,940,951,953
345	CARHOME	P	296,532,554
559	CARHOME2	P	564
153	CARPOS	D	569,897,978
145	CARRIAGE	D	457,460,463,503,506,889,977,989
928	CARRIAGE3	P	888
939	CARRIAGE4	P	936
954	CARRIAGE5	P	952
958	CARRIAGE6	P	956
196	CARSEIL	A	975
197	CARSPD1	A	623,1293
198	CARSPD2	A	1294
199	CARSPD3	A	1295
200	CARSPD4	A	1296
201	CARSPD5	A	1297
202	CARSPD6	A	1298
203	CARSPD7	A	1299
204	CARSPD8	A	1300
1292	CARSPEEDS	P	959
146	CARSTAT	D	886,907,911,979,981,990
147	CARSTAT_BUSY	A	887,905,910
148	CARSTAT_LEFT	A	906,910,933
149	CARSTAT_SETTLE	A	931,980
150	CARTICKS	D	923,929,962,966,967,976
152	CARTOGO	D	153,920,941,950
621	CAR_DELAY	P	551,561
625	CAR_DELAY2	P	628
988	CAR_DUNE	P	898,932
991	CAR_END	P	924,930,968,982
909	CAR_LEFT	P	904
974	CAR_SETTLE	P	942
918	CAR_SELVARS	P	908
243	CLEAR_MEM	P	247
160	CLOCK	D	161,509,513,740,743
1023	CONTINUE	P	1006
	COPY_BUFFER	P	325
173	CR	A	376,1248,1252,1256,1260,1264,1266
793	CW	P	788
56	DDR1	A	255
57	DDR2	A	264
60	DDR3	A	

LINE#	SYMBOL	TYPE	REFERENCES
154	MODE	D	275,331,394,396,400,402,406,417,428,430
156	MODE_REVERSE	A	395,401,407,418,429
155	MODE_TEST	A	274,332
195	MOTORS	A	253,517,531,536,592,614,685,707
191	MSEC11	A	222
192	MSEC15	A	716
231	M_LEN	E	
231	M_SIG	E	324,511,522
778	NEG	P	773
231	NET_IN_RUFF	E	
286	NOT_SELF_TEST	P	271
502	NO_CHAR	P	
1367	NULL	P	
74	OCR	A	306,732
76	P3CSR	A	
159	PHANTOM	D	298,410,413,421,424,432,452,459,505
120	PLATEN	D	302,436,439,442,445,464,1103,1184
1100	PLATPOS	P	
121	PLATSTAT	D	1101,1107,1138,1165,1177,1183
122	PLATSTAT_RUN1	A	1106,1113
123	PLATSTAT_RUN2	A	1115,1137
125	PLATSTAT_SETTLE	A	1119,1176
124	PLATSTAT_STOP	A	1117,1164
126	PLATTHICKS	D	1163,1169,1175,1181,1222,1223
180	PLWIDTH	A	411,453
226	PL_BRAKE_COUNT	A	1162
1112	PL_CONTINUE	P	1102
1186	PL_END	P	1136,1142,1154,1166,1170,1178,1182
1141	PL_END_ISLE	P	1104,1110,1121
1128	PL_RUN1	P	1114
1146	PL_RUN2	P	1116
1227	PL_RUN_OFF	P	
1232	PL_RUN_ON	P	1226
1180	PL_SETTLE	P	1120
227	PL_SETTLE_COUNT	A	1174
225	PL_SPEED	A	1225
1168	PL_STOP	P	1116
228	PL_TIMEDOUT	A	1108,1139
58	PORT1	A	95
59	PORT2	A	
62	PORT3	A	97
63	PORT4	A	99
885	POSCAR	P	
750	POSWHEEL	P	
451	PRINTABLE	P	373
456	PRINTABLE1	P	458
367	PRINT_ONE	P	322
231	PR_MAC	E	1376
1221	PULSE_MOTOR	P	1133,1151
93	RAMCR	A	
91	RDATA	A	
241	RESET	P	1381
427	RETURN	P	377
399	REVERSE	P	385
1056	RFIRE	P	1034
222	RIBFIRE	A	1066
223	RIBREL	A	1079

LINE#	SYMBOL	TYPE	REFERENCES
77	RMCR	A	278,288,1205
79	RMCR_CC0	A	277,287,1204
78	RMCR_CC1	A	
81	RMCR_SS0	A	
80	RMCR_SS1	A	
671	ROT_CCW	P	640,653,817
693	ROT_CW	P	820
1072	RREL	P	1036
16	SHANNON	A	114,162,230,268,317,323,337,487,496,1239,1374
175	SI	A	388
174	SO	A	384,1246,1250,1254,1258,1262
374	SOME_2	P	372
177	SP	A	371,449,470,759,863
405	SPACE	P	375,478
1327	SPOKES	P	759,863
112	STACK	D	249
111	STACKSPACE	D	
578	STEP_LEFT	P	560,938
600	STEP_RIGHT	P	550,935
1244	STRING	P	335,338
1267	STRING_END	P	338
64	TCSR	A	282,292,308,729,733,1193,1203
68	TCSR_EIC1	A	
69	TCSR_EOC1	A	
70	TCSR_ET01	A	307,1192
65	TCSR_ICF	A	
71	TCSR_IEDG	A	
66	TCSR_OCF	A	
72	TCSR_OLVL	A	
67	TCSR_TOF	A	
92	TDATA	A	
190	TICK	A	305,623,716,731
510	TIMEOUT	P	514
73	TIMER	A	304,622,626,715,719,730
82	TRCSR	A	280,290,1207
84	TRCSR_UNFE	A	
83	TRCSR_RDRF	A	
87	TRCSR_RE	A	279,289,1206
86	TRCSR_RIE	A	289
85	TRCSR_TDRE	A	
89	TRCSR_TE	A	279,289,1206
88	TRCSR_TIE	A	
90	TRCSR_WU	A	
172	VT	A	386
161	WANT_TIMER	D	624,627,717,720
1200	WE_DIED	P	132,1150
128	WHEEL	D	455,462,754,862,877
652	WHEEL2	P	657
810	WHEEL3	P	753
821	WHEEL4	P	818
836	WHEEL5	P	834
840	WHEEL6	P	838
134	WHEELGONE	D	803,822,833,835
636	WHEELHOME	P	299,533,644
136	WHEELPOS	D	662,763,866
1308	WHEELSPEEDS	P	841
133	WHEELTICKS	D	805,811,844,851,852,861

LINE#	SYMBOL	TYPE	REFERENCES
135	WHEELTGG0	D	136,802,823,832
772	WHEELXX	P	764
714	WHEEL_DELAY	P	641,654
718	WHEEL_DELAY2	P	721
206	WHSETL	A	860
207	WHSPD1	A	1309
208	WHSPD2	A	1310
209	WHSPD3	A	1311
210	WHSPD4	A	1312
211	WHSPD5	A	1313
212	WHSPD6	A	1314
213	WHSPD7	A	1315
214	WHSPD8	A	1316
129	WHSTAT	D	751,791,795,867,869,878
130	WHSTAT_BUSY	A	752,789,794
131	WHSTAT_CW	A	790,794,815
132	WHSTAT_SETTLE	A	813,868
876	WH_DONE	P	765,814
879	WH_END	P	806,812,853,870
859	WH_SETTLE	P	824
801	WH_SETVARS	P	792

LOCATION OBJECT CODE LINE SOURCE LINE

```

1 ^6801^
2 ;
3 ; external routines referenced
4 ;
5 EXT MPR_TR_TRANS
6 EXT MPR_TR_TCU
7
8 ;
9 ; global data areas defined
10 ;
11 GLB CUKKRENT_STATE
12 GLB NET_IN_BUFF
13 ;
14 ; external data areas used
15 ;
16 EXT M_SIG,M_LEN
17
18 NODE_ADDR EQU 2
19
20 ;
21 ; message scenarios equates
22 ;
23 MN_RESET EQU 000H*16+NODE_ADDR
24 MN_STATUS EQU 001H*16+NODE_ADDR
25 MN_ACK EQU 002H*16+NODE_ADDR
26 MN_CLR EQU 003H*16+NODE_ADDR
27 MN_RECEIVE EQU 004H*16+NODE_ADDR
28 MN_CANCEL EQU 005H*16+NODE_ADDR
29 MN_SEND EQU 006H*16+NODE_ADDR
30 MN_NACK EQU 007H*16+NODE_ADDR
31 MN_READY EQU 00DH*16+NODE_ADDR
32
33 NM_STATUS EQU 008H*16+NODE_ADDR
34 NM_ACK EQU 009H*16+NODE_ADDR
35 NM_CANCEL EQU 00AH*16+NODE_ADDR
36 NM_SEND EQU 00BH*16+NODE_ADDR
37 NM_NACK EQU 00CH*16+NODE_ADDR
38
39 ; local equates
40 ;
41 ;
42 DATA_AVAIL EQU 001H
43
44 RDRF_INT EQU 0
45 TDRE_INT EQU 1
46 IGN_RDRF_INT EQU 2
47
48 CNTRL EQU 0
49 LENGTH_IN_HI EQU 1
50 LENGTH_IN_LO EQU 2
51 DATAB EQU 3
52 CHKSUM_IN EQU 4
53 STATOUT EQU 5
54 CHKSUM_OUT EQU 6
55 WAIT_ACK_NACK EQU 7
56
57 PRUG

```

; PRINTER ADDR = 2

```

;command.control (reset)
;command.control (status)
;command.control (ack)
;command.control (clr)
;command.control (receive)
;command.control (cancel)
;command.data (send)
;command.control (nack)
;command.control (ready)

;response.control (status)
;response.control (ack)
;response.control (cancel)
;response.data (send)
;response.control (nack)

```


LOCATION OBJECT CODE LINE SOURCE LINE

```

58
59 PR_MAC
60 PR_MAC:
61 GLB PR_MAC
62 INT_FLAG,D
63 EXP_KDRF
64 DELCA
65 EXP_TDRE
66
67 ;**** HAD AN RDRF THAT WE WANT TO IGNORE ****
68
69 LDAA #RDRF INT
70 STAA INT_FLAG,D
71
72 JMP END_PR_MAC
73
74 EXP_RDRF:
75 *****JSR
76
77 ; local equates
78 ;
79 ;
80 <00F> EQU 00FH
81 <00F0> EQU 0F0H
82
83 <0040> EQU 0100000B
84
85 SEC
86 LDAB 011H,D
87 LDAA 012H,D
88
89 ANDB #ORFE
90 BEQ NO_ORFE
91
92 GLB BREAK_ORFE
93
94 BREAK_ORFE:
95
96 LDAA #CNTRL
97 STAA CURRENT_STATE,D
98
99 JMP SET_WAKEUP
100 NO_ORFE:
101 LDAB CURRENT_STATE,D
102 BNE ENDF_CNTRL
103 TAB
104 ANDA #ADDR_MASK
105 CMPA #NODE_ADDR
106 BNE ELSE_NOTADDR
107 TRA
108
109 SEC
110 BRA
111 ELSE_NOTADDR:
112 CLC
113 ENDF_ADDR:
114 ENDF_CNTRL:
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```

LOCATION OBJECT CODE LINE      SOURCE LINE
002E 250B      115      RCS      BYTE_FOR_US      ;1      if net_byte_in = for our address
116
0030      117      SET_WAKEUP:
0030 D611      118      LDAB      011H,D
0032 CA01      119      ORAB      #0000001B
0034 D711      120      STAB      011H,D
121
0036 7E0143      122      JMP      END_PR_MAC
123
0039      124      EXP_TDRE:
0039 9611      125      LDAA      011H,D
126
003B      127      BYTE_FOR_US:
129
003B D600      130      LDAB      CURRENT_STATE,D
003D 58      131      LSLB
003E CE0046      132      LDX      #STATE_TABLE
0041 3A      133      ABX
0042 EE00      134      LDX      0,X
0044 6E00      135      JMP      0,X
136
0046      137      STATE_TABLE:
0046 0056      138      FDB      CONTROL
0048 0084      139      FDB      LENGTH_IN_HI
004A 00BF      140      FDB      LENGTH_IN_LO
004C 00CF      141      FDB      DATA_IN
004E 00EB      142      FDB      CHK_SUM_IN
0050 0107      143      FDB      STAT_OUT
0052 0125      144      FDB      CHK_SUM_OUT
0054 013B      145      FDB      GOT_ACK_NACK
146
0056      147      CONTROL:
0056 8102      148      CMPA      #MN_RESET
0058 2605      149      BNE
150
005A FEF7FE      151      LDX      OFFFEH,E
005D 6E00      152      JMP      0,X
153
005F      154      NOT_RESET:
005F 81D2      155      CMPA      #MN_READY
0061 2715      156      BEQ      CHK_CTS
0063 8162      157      CMPA      #MN_SEND
0065 2726      158      BEQ      REC_DATA
0067 8112      159      CMPA      #MN_STATUS
0069 2729      160      BEQ      SEND_STATUS
161
006B 86C2      162      LDAA      #NM_NACK
006D BD0000      163      JSR      MPR_TR_TRANS
0070 2503      164      RCS      ERRI
0072 BD0000      165      JSR      MPR_TR_TCU
166
0075      167      ERRI:
0075 7E0143      168      JMP
169
0078      170      CHK_CTS:
0078 9600      171      LDAA      M_SIG,D

```

```

;1      if net_byte_in = for our address
;      SET WAKE-UP FLAG
;      ALLOW WRITE TO TRD
;      TO CLEAR TDRE
;2      case CURRENT_STATE of
;      check for control case
;      TABLE LOOK-UP
;      INFO STATE_TABLE
;      WHERE WE SHOULD GO
;      NET BYTE IN IS COMMAND
;      EXPECTING HI BYTE OF LENGTH
;      LO
;      EXPECTING DATA BYTES IN
;      EXPECTING CHECKSUM IN
;      SENDING STATUS OUT
;      SENDING CHECKSUM OUT
;      WAITING FOR ACK/NACK
;2      control : begin
;      REQUEST FOR STATUS
;      BAD COMMAND TO ME
;      chk_cts : begin
;      if NIM_M_SIG = 0
;2

```



```

LOCATION OBJECT CODE LINE SOURCE LINE
00C1 9701 STAA M_LEN+1,D 229
00C3 C603 LDAB #DATAIN 230
00C5 D700 STAB CURRENT_STATE,D 231
00C7 7F0004 CLR DATA_INDEX,D 232
00CA 7F0003 CLR CHK_SUM,D 233
00CD 2074 BRA END_PR_MAC 234
00CF DATA_IN: 235
00CF CE0006 LDX #NET_IN_BUFF 236
00D2 D604 LDAB DATA_INDEX,D 237
00D4 3A ABX 238
00D5 A700 STAA 0,X 239
00D7 9803 EORA CHK_SUM,D 240
00D9 9703 STAA CHK_SUM,D 241
00DB 7C0004 INC DATA_INDEX,D 242
00DE DE01 LDX LOC_LEN,D 243
00E0 09 DEX 244
00E1 DF01 STX LOC_LEN,D 245
00E3 2604 BNE MORE_DATA_IN 246
00E5 8604 LDAA #CHKSUM_IN 247
00E7 9700 STAA CURRENT_STATE,D 248
00E9 MORE_DATA_IN: 249
00E9 2050 BRA END_PR_MAC 250
00EB CHK_SUM_IN: 251
00EB 9103 CMPA CHK_SUM,D 252
00ED 2608 BNE ELSE_NEQU 253
00EF 8601 LDAA #DATA_AVAIL 254
00F1 9700 STAA M_SIG,D 255
00F3 8692 LDAA #NM_ACK 256
00F5 2002 BRA ENDIF_CSNUM 257
00F7 ELSE_NEQU: 258
00F7 86C2 LDAA #NM_NACK 259
00F9 ENDIF_CSNUM: 260
00F9 B00000 JSR MPR_TR_TRANS 261
00FC 2507 BCS ERR3 262
00FE B00000 JSR MPR_TR_TCU 263
0101 8600 LDAA #CTRL 264
0103 9700 STAA CURRENT_STATE,D 265

```

```

;2 data_in : begin
;3 ram_memory [NIM_M_DATA] = net_byte_in
; get the base pointer into ram_memory
; get the index from the base
; form the effective address
; put net_byte_in into ram_memory
csnum = csnum XOR net_byte_in
NIM_M_DATA = NIM_M_DATA + 1
endif
end
;2 if LOC_LEN = 0
;3 CURRENT_STATE = chk_sum
;4 get the chk_sum constant
; store the constant
;3 endif
;2 ;2 chk_sum : begin
;3 if csnum = net_byte_in
;4 compare with net_byte_in
;4 send ACK
;3 else send NACK
;3 ;4 endif
;3 ;3 CURRENT_STATE = idle
;4 get the idle constant
;5 store the constant
;6 CURRENT_STATE = control
;3 ;3

```

LOCATION OBJECT CODE LINE SOURCE LINE

```

286
287 ERR3:
288
289
290 STAT_OUT:
291 LDX #STAT_PKT
292 LDAB DATA_INDEX,D
293 ABX
294 LDAA 0,X
295 STAA 013H,D
296
297 EORA CHK_SUM,D
298 STAA CHK_SUM,D
299
300 INC DATA_INDEX,D
301
302 LDX LOC_LEN,D
303 DEX
304 STX
305
306 BNE MORE_STAT_OUT
307
308 LDAA #CHKSUM_OUT
309 STAA CURRENT_STATE,D
310
311 MORE_STAT_OUT:
312
313
314
315
316
317
318
319
320
321 ;
322 ;
323 ;
324
325 LDAA #00011011B
326 STAA 011H,D
327
328 LDAA #RDRF_INT
329 STAA INT_FLAG,D
330
331 LDAA #WAIT_ACK_NACK
332 STAA CURRENT_STATE,D
333
334
335
336
337 GOT_ACK_NACK:
338 LDAB #CTRL
339 STAB CURRENT_STATE,D
340
341 LDAA #00011011B
342 STAA 011H

```

; SOURCE OF STATUS OUT
 ; WHICH BYTE THIS TIME
 ; GET INDEXED ADDR
 ; A = DATA BYTE TO GO
 ; SHIP IT

; ACCUMULATE CHECKSUM
 ;

; NEXT BYTE NEXT TIME
 ;

; DEC COUNT OF BYTES SENT
 ;
 ; SAVE NEW BYTE COUNT
 ;

; MORE TO DO
 ;

; SEND CHECKSUM NEXT TIME
 ;

; OUTPUT CHECKSUM
 ;

; RESET RDRF (HOPEFULLY...)

; NEXT INT SHOULD BE RDRF
 ;

; NEXT BYTE IN SHOULD BE
 ; ACK/NACK ON WHAT WE
 ; SENT

; DONE
 ;

; NEXT BYTE IN IS NEW
 ; SCENARIO

LINE#	SYMBOL	TYPE	REFERENCES
80	ADDR_MASK	A	104
94	BREAK_DRFE	P	92
128	BYTE_FOR_US	P	15
52	CHKSUM_IN	A	257
54	CHKSUM_OUT	A	308
170	CHK_CTS	P	156
367	CHK_SUM	D	211,235,246,247,265,297,298,315
263	CHK_SUM_IN	P	142
314	CHK_SUM_OUT	P	144
81	CMND_MASK	A	95,283,338
48	CNTRL	A	138
147	CONTROL	P	138
365	CURRENT_STATE	D	11,96,101,130,187,203,223,232,258,284,309,332,339,363
51	DATAIN	A	231
42	DATA_AVAIL	A	268
239	DATA_IN	P	141
368	DATA_INDEX	D	209,234,242,249,292,300
175	ELSE_NCTS	P	172
274	ELSE_NEQU	P	266
111	ELSE_NOTADDR	P	106
113	ENDIF_ADDR	P	110
114	ENDIF_CNTRL	P	102
277	ENDIF_CSNUM	P	272
177	ENDIF_CTS	P	174
346	END_PR_MAC	P	72,122,168,183,188,216,225,237,261,288,312,335
167	ERR1	P	164
182	ERR2	P	179
287	ERR3	P	279
74	EXP_RDRF	P	63
124	EXP_IDRE	P	65
337	GOT_ACK_NACK	P	145
46	IGN_RDRF_INT	A	
369	INT_FLAG	D	61,70,206,329
49	LENGTHIN_HI	A	186
50	LENGTHIN_LO	A	222
218	LENGTH_IN_HI	P	139
227	LENGTH_IN_LO	P	140
366	LOC_LEN	D	200,219,228,251,253,302,304
25	MN_ACK	A	
28	MN_CANCEL	A	
26	MN_CLR	A	
30	MN_NACK	A	155
31	MN_READY	A	
27	MN_RECEIVE	A	
23	MN_RESET	A	148
29	MN_SEND	A	157
24	MN_STATUS	A	159
260	MORE_DATA_IN	P	255
311	MORE_STAT_OUT	P	306
6	MPR_TR_ICU	E	165,180,280
5	MPR_TR_TRANS	E	163,178,278
16	M_LEN	E	220,229
16	M_SIG	E	171,269
373	NET_IN_BUFF	D	12,241,371
34	NM_ACK	A	173,271
35	NM_CANCEL	A	
37	NM_NACK	A	162,176,275

LINE#	SYMBOL	TYPE	REFERENCES
36	NM_SEND	A	
33	NM_STATUS	A	
18	NODE_ADDR	A	23,24,25,26,27,28,29,30,31,33,34,35,36,37,105
154	NOT_RESET	P	149
100	NO_ORFE	P	90
83	ORFE	A	89
60	PR_MAC	P	59
44	RDRF_INT	A	69,328
185	REC_DATA	P	158
190	SEND_STATUS	P	160
117	SET_WAKEUP	P	98
137	STATE_TABLE	P	132
53	STATOUT	A	202
290	STAT_OUT	P	143
349	STAT_PKT	P	213,291,356
356	STAT_PKT_SIZE	A	199
45	TDRE_IN1	A	205
55	WAIT_ACK_NACK	A	331

LOCATION OBJECT CODE LINE SOURCE LINE

```

1 ^6801^
3 NAME ^Rev 03 - RPD^
4
5 De_MPR_TR_TRANS MACRO ;Header Rev. 4
6 .GOTO Ede_MPR_TR_TRANS
7
8 Project: NET, 83-101
9
10 *****
11 *****
12 MPR ... TR ... TRANS DLS
13 *****
14 *****
15 *****
16
17 Rev History
18 Rev. Date Name Change
19 3 20Jul740p RPD removed LIST directives
20 2 19Jul2053 JIM Printer MAC started,
21 1 13Jul835a RPD converted pseudo code to 6801 code
22 0 12JUL1236 DLS Initial Pseudo code
23 Ede_MPR_TR_TRANS MEND

```

```

LOCATION OBJECT CODE LINE SOURCE LINE
25 *****
26 *
27 * MODULE NAME:
28 *
29 * MPR_TR_TRANS
30 *
31 * INPUTS:
32 *
33 * NET_BYTE_OUT (REG_A)
34 *
35 * FUNCTION(S):
36 *
37 * 1. TO SEND A BYTE OUT OVER THE NETWORK.
38 *
39 * OUTPUTS:
40 *
41 * NET_BYTE_OUT (LOCATION 13)
42 *
43 * CALLS:
44 *
45 * NONE.
46 *
47 * CALLED BY:
48 *
49 * MPR_ACH_SEQ
50 * MPR_NIM_READ
51 *
52 * NOTES:
53 *
54 * NONE.
55 *
56 *****
57 *****
58 *****
59 *
60 * PSEUDO CODE:
61 *
62 * MPR_TR_TRANS:
63 * REPEAT_UNTIL_SET:
64 *
65 * IF MEM(11).5=0 THEN GOTO REPEAT_UNTIL_SET;
66 * ENDIF;
67 * MEM(13)=REG_A;
68 *
69 *
70 *
71 * RETURN;
72 *
73 *****

```

LOCATION OBJECT CODE LINE SOURCE LINE

```

75 + ; INCLUDE PGO_EQU
+ ; 6801 internal register equates (page 0)
+ ;
+ P1_DIR EQU 000H ;port 1 data direction register
+ P1_DATA EQU 002H ;port 1 data register
+ P2_DIR EQU 001H ;port 2 data direction register
+ P2_DATA EQU 003H ;port 2 data register
+ P3_DIR EQU 004H ;port 3 data direction register
+ P3_DATA EQU 006H ;port 3 data register
+ P4_DIR EQU 005H ;port 4 data direction register
+ P4_DATA EQU 007H ;port 4 data register
+ T_CNTRLSTAT EQU 008H ;timer control and status register
+ T_CNTRHGH EQU 009H ;counter high byte
+ T_CNTRLOW EQU 00AH ;counter low byte
+ T_OCMPHGH EQU 00BH ;output compare register high byte
+ T_OCMPLOW EQU 00CH ;output compare register low byte
+ T_ICAPHGH EQU 00DH ;input capture register high byte
+ T_ICAPLOW EQU 00EH ;input capture register low byte
+ P3_CNTRLSTAT EQU 00FH ;port 3 control and status register
+ SCI_RM EQU 010H ;rate and mode control register
+ SCI_TR_CS EQU 011H ;transmit/receive control and status register
+ SCI_RX EQU 012H ;receive data register
+ SCI_TX EQU 013H ;transmit data register
+ RAM_CNTL EQU 014H ;RAM control register
76
77 ; local equates
78 ;
79 ;
80 TDRE_MASK EQU 020H ;"transmit_data_register_empty" mask
81

```

```

LOCATION OBJECT CODE LINE SOURCE LINE
83          PRUG
84          GLR          MPR_TR_TRANS
85          MPR_TR_TRANS:
86          PSHX          # (2*160)/(3+3+3+2+3)
87          LDX          ; SAVE X JUST IN CASE
88          ; ALLOW 2 BYTE TIMES
89          REPEAT:      ; 1 REPEAT
90          DEX          ; TIME UP ???
91          BEQ          ; YUP
92          HAVE_TDRE_ERR
93          ;
94          LDAB          SCI_TR_CS,D
95          ANDB          #TDRE_MASK
96          BEQ          REPEAT
97          *
98          STAA          SCI_TX,D
99          ;
100         CLC
101         BRA          END_TR
102         ;
103         ;
104         HAVE_TDRE_ERR:
105         CLEAN UP UART PORTS
106         ;
107         EXT          CLEAN_UART_HW
108         ;
109         JSR          CLEAN_UART_HW
110         ;
111         SEC
112         ;
113         END_TR:
114         PULX
115         RTS

Errors= 0
    
```

LINE#	SYMBOL	TYPE	REFERENCES
107	CLEAN_UART_HW	E	109
113	END_TR	P	102
104	HAVE_TDRE_ERR	P	91
85	MPR_TR_TRANS	P	84
89	REPEAT	P	96
	SCI_TR_CS	A	94
	SCI_TX	A	98
80	TDRE_MASK	A	95

LOCATION OBJECT CODE LINE SOURCE LINE

```

1 ^6801^
3 NAME ^Rev 01 - RPD^
4
5 De_MPR_TR_TCU MACRO .GOTO Ede_MPR_TR_TCU ;Header Rev, 4
6
7
8 Project: NET, B3-101
9
10
11
12 MPR ...TR ...TCU RPD
13
14
15
16 Rev History
17 Rev. Date Name Change
18 1 20Jul800P RPD created from MPR file
19 0 19Jul835p RPD Initial Pseudo code and code
20
21 Cde_MPR_TR_TCU MEND

```

LOCATION OBJECT CODE LINE SOURCE LINE

```

23 *****
24 *
25 * MODULE NAME:
26 *
27 * MPR_TR_ICU (transmit clean up)
28 *
29 * INPUTS:
30 *
31 * none
32 *
33 * FUNCTION(S):
34 *
35 * 1. Clears the "receive data register full" flag of the
36 * 6801 SCI after a transmission sequence (1 or more
37 * bytes). The flag is set as a result of sending a byte
38 * out and receiving the same byte in on the common NET
39 * line used for sending and receiving.
40 *
41 * OUTPUTS:
42 *
43 * SCI control/status register bit 7 = 0
44 *
45 * CALLS:
46 *
47 * none
48 *
49 * CALLED BY:
50 *
51 * MPR_ACM_R
52 * (all routines calling MPR_TR_TRANS)
53 *
54 * NOTES:
55 * 1 - This sequence follows the procedure described in
56 * hardware manuals for clearing the flag. Which is:
57 * step 1) read the SCI control status register
58 * step 2) read the SCI receive data register
59 * 2 - The MAC modules are responsible for calling this
60 * module after doing a transmit function to avoid
61 * reading itself when other data is expected.
62 *
63 *****

```

```

LOCATION OBJECT CODE LINE SOURCE LINE
65 *****
66 * PSEUDO CODE:
67 *
68 *
69 * begin
70 * wait for IDRE = 1
71 * clear KDRF (from 2nd to the last byte)
72 * wait for KDRF = 1
73 * read in the received byte (from very last byte)
74 * end
75 *
76 *****
77
78 + ; INCLUDE PGO_EQU
79 + ;
80 + ; 6801 internal register equates (page 0)
81 +
82 + P1_DIR EQU 000H ;port 1 data direction register
83 + P1_DATA EQU 002H ;port 1 data register
84 + P2_DIR EQU 001H ;port 2 data direction register
85 + P2_DATA EQU 003H ;port 2 data register
86 + P3_DIR EQU 004H ;port 3 data direction register
87 + P3_DATA EQU 006H ;port 3 data register
88 + P4_DIR EQU 005H ;port 4 data direction register
89 + P4_DATA EQU 007H ;port 4 data register
90 + T_CNTRLSTAT EQU 008H ;timer control and status register
91 + T_CNTRLHIGH EQU 009H ;counter high byte
92 + T_CNTRLLOW EQU 00AH ;counter low byte
93 + T_OCMPHIGH EQU 00BH ;output compare register high byte
94 + T_OCMPLOW EQU 00CH ;output compare register low byte
95 + T_ICAPHIGH EQU 00DH ;input capture register high byte
96 + T_ICAPLOW EQU 00EH ;input capture register low byte
97 + P3_CNTRLSTAT EQU 00FH ;port 3 control and status register
98 + SCI_RM EQU 010H ;rate and mode control register
99 + SCI_FR_CS EQU 011H ;transmit/receive control and status register
100 + SCI_RX EQU 012H ;receive data register
101 + SCI_TX EQU 013H ;transmit data register
102 + RAM_CNTRL EQU 014H ;RAM control register
103
104 ; local equate
105 ;
106 TDRE_MASK EQU 020H
107
108 PROG MPR_FR_TCU ;
109 GLB
110 PSHX
111 LDX #(3*160)/(3+3+3+2*3) ; ALLOW 3 BYTE TIMES
112
113
114
115
116
117
118
119
120

```


LOCATION OBJECT CODE LINE SOURCE LINE

```

0004          91 REPEAT:
0004 09      DEX
0005 2713    REQ      TDRE_ERR
          94
0007 D611    LDAB     SCI_TR_CS,D
0009 C420    ANDB     #TDRE_MASK
000B 27F7    REQ      REPEAT
          98
000D D612    LDAB     SCI_RX,D      ;reset RDRF from 2nd to last byte
          100
000F          101 REPEAT1:
000F 09      DEX
0010 2708    REQ      TDRE_ERR
          104
0012 D611    LDAB     SCI_TR_CS,D      ;1 WAIT FOR RECEIVE DATA REGISTER FULL
0014 2AF9    BPL     REPEAT1
          107
0016 D612    LDAB     SCI_RX,D      ;1 EMPTY RECEIVED DATA REGISTER AND CLEAR RDRF BIT
          109
0018 38      PULX
          111
0019 39      RTS
          113
001A          114 TDRE_ERR:
001A 8D02    CLEAN UP UART PORTS
001C 38      BSR     CLEAN_UART_HW
          117
001D 39      PULX
          119
          120
          121
          122
          123
001E          124 CLEAN_UART_HW:
001E D611    LDAB     011H,D
0020 D612    LDAB     012H,D
          127
0022 C61B    LDAB     #00011011B
0024 D711    STAB     011H,D
          130
          131
          132
          133
0026 C600    EXT     CURRENT_STATE
0028 D700    LDAB     #0
          134
          135
002A 39      STAB     CURRENT_STATE,D
          136

```

Errors= 0

LINE#	SYMBOL	TYPE	REFERENCES
124	CLEAN_UART_HW	P	116,122
131	CURRENT_STATE	E	134
86	MPR_TR_TCU	P	85
91	REPEAT	P	97
101	REPEAT1	P	106
	SCI_RX	A	99,108
	SCI_TR_CS	A	95,105
114	TDRE_ERR	P	93,103
82	TDRE_MASK	A	96

LOCATION OBJECT CODE LINE SOURCE LINE

```

1 ^6801^
3 NAME ^Rev 00 - DLS^
4
5 De_D_MAC MACRO ;Header Rev. 4
6 .GOTO Ede_D_MAC
7
8 Project: NET, B3-101
9
10 ***
11 ***
12 *** D_MAC ***
13 ***
14 ***
15
16 Rev History
17 Rev. Date Name Change
18 0 13Jul1815 DLS Initial Pseudo code
19
20 Ede_D_MAC MEND

```

```

LOCATION OBJECT CODE LINE SOURCE LINE
22 * *****
23 * *
24 * * MODULE NAME:
25 * *
26 * * D_MAC
27 * *
28 * * FUNCTION(S):
29 * *
30 * * 1. TO DECLARE THE DATA AREA "NIM_BLOCK."
31 * * 2. TO DECLARE THE D1_MODE_WORD.
32 * *
33 * * NOTES:
34 * *
35 * * 1. NIM_BLOCK IS USED AS THE INTERFACE BETWEEN THE
36 * * MEDIUM ACCESS CONTROLLER AND THE RESIDENT APPLICATION
37 * * PROGRAM.
38 * *
39 * * 2. THE INSTALLER IS RESPONSIBLE FOR LOCATING THIS DATA
40 * * MODULE SO THAT THE LAST BYTE ENDS AT LOCATION 127 (DEC).
41 * *
42 * *****

```

LOCATION OBJECT CODE LINE SOURCE LINE

```

44 GLB D_MAC
45 GLB D1_MODE_WORD
46 GLB NIM_BLOCK
47 GLB A_LEN
48 GLB A_DATA
49 GLB A_SIG
50 GLB CNFG_WORD
51 GLB M_SIG
52 GLB M_LEN
53 DATA
54 D_MAC:
55 *****
56 *
57 * DATA WORD:
58 *
59 * D1_MODE_WORD
60 *
61 * FUNCTION:
62 *
63 * CONTAINS THE STATE OF SEQUENCER PROCESSING
64 *
65 *****
66 D1_MODE_WORD EQU $
67 RMB 1

```

0000

0000

<0000>

LOCATION OBJECT CODE LINE SOURCE LINE

```

+ *****
+ *
+ * DATA ELEMENT DEFINITIONS:
+ *
+ * M_SIG:
+ * -----
+ * 0- APP READY FOR MORE DATA. (APP WRITES)
+ * 1- APP IS NOT READY FOR MORE DATA. (MAC WRITES)
+ *
+ * M_DATA
+ * -----
+ * 2 BYTE POINTER TO DATA.
+ *
+ * M_LEN:
+ * -----
+ * COUNT OF BYTES IN MAC BUFFER.
+ *
+ * NOTES:
+ *
+ * NONE.
+ *
+ *****

```


REFERENCES

LINE#	SYMBOL	TYPE	REFERENCES
72	A_DATA	D	48
73	A_LEN	D	47
71	A_SIG	D	49
74	CNFG_WORD	D	50
66	D1_MODE_WORD	D	45
54	D_MAC	D	44
76	M_LEN	D	52
75	M_SIG	D	51
70	NIM_BLOCK	D	46

FILE/PROG NAME	PROGRAM	DATA	COMMON	ABSOLUTE	DATE	TIME	COMMENTS
DAISY4:PADAMP	F800	0080		FFF0-FFF1 FFFA-FFFF FFFE-FFFF	Mon, 7 Nov 1983,	15:47	Rev 16 GRW
PR_MAC:PADAMP next address	FDD8 FF21	00E6 00FC			Mon, 7 Nov 1983,	16:03	
MPR_TR_TR:PADAMP MPR_TR_TC:PADAMP next address	FF21 FF39 FF64				Mon, 7 Nov 1983, Mon, 7 Nov 1983,	16:02 16:00	Rev 03 - RPD Rev 01 - RPD
D_MPR:PADAMP next address		00FC 0100			Mon, 7 Nov 1983,	15:59	Rev 00 - DLS

XFER address= 0000 Defined by DEFAULT
 absolute & link_com file name=PKA:PADAMP
 Total# of bytes loaded= 07EA

REFERENCES

DEF BY

R VALUE

SYMBOL

A_DATA	D 00FD	D_MPR:PADAMP
A_LEN	D 00FD	D_MPR:PADAMP
A_SIG	D 00FD	D_MPR:PADAMP
BREAK_ORFE	P FDEF	PR_MAC:PADAMP
CLEAN_QUART_HW	P FF57	MPR_TR_TC:PADAMP
CNFG_WORD	D 00FD	D_MPR:PADAMP
CURRENT_STATE	D 00E6	PR_MAC:PADAMP
D1_MODE_WORD	D 00FC	D_MPR:PADAMP
D_MAC	D 00FC	D_MPR:PADAMP
MPR_TR_ICU	P FF39	MPR_TR_TC:PADAMP
MPR_TR_TRANS	P FF21	MPR_TR_TR:PADAMP
M_LEN	D 00EE	D_MPR:PADAMP
M_SIG	D 00FD	D_MPR:PADAMP
NET_IN_BUFF	D 00EC	PR_MAC:PADAMP
NIM_BLOCK	D 00FD	D_MPR:PADAMP
PR_MAC	P FDD8	PR_MAC:PADAMP

MPR_TR_TR:PADAMP

MPR_TR_TC:PADAMP

PR_MAC:PADAMP

PR_MAC:PADAMP

PR_MAC:PADAMP

DAISY4:PADAMP

DAISY4:PADAMP

DAISY4:PADAMP

DAISY4:PADAMP